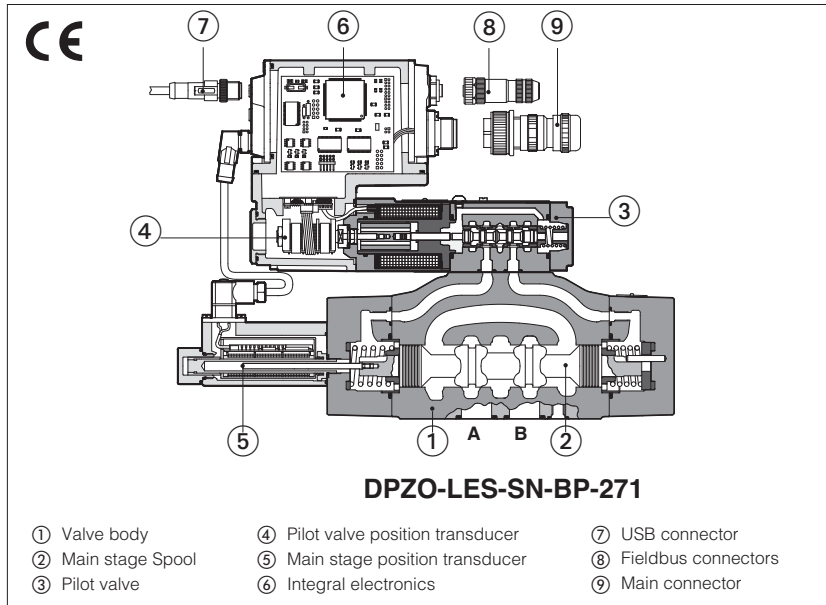


Two stage proportional directional valves high performance

digital with two position transducers and **positive spool overlap**, rugged design



DPZO-LEB, DPZO-LES

High performance two stage digital proportional valves specifically designed for high speed closed loop controls.

They are equipped with two LVDT position transducers (pilot valve and main stage) and positive spool overlap for best dynamics in directional controls and not compensated flow regulations.

The integral digital electronic driver performs the valve's hydraulic regulation according to the reference signal and assures valve-to-valve interchangeability thanks to the factory presetting.

High performances valves are available in LEB basic execution with analog reference signals and USB port for software functional parameters setting or in LES full execution which includes also optional alternated P/Q controls and fieldbus interfaces for functional parameters setting, reference signals and real-time diagnostics.

Size: **10 to 35**

Max flow: **180 to 3500 l/min**

Max pressure: **350 bar**

1 MODEL CODE for STANDARD SPOOLS

DPZO	-	L	-	ES	-	SN	-	NP	-	2	-	71	-	L	-	5	/	*	/	*	/	*
-------------	---	----------	---	-----------	---	-----------	---	-----------	---	----------	---	-----------	---	----------	---	----------	---	----------	---	----------	---	----------

Two stage proportional directional valve

L = closed-loop two LVDT transducer

Integral digital drivers:
EB = basic (1)
ES = full

Alternated P/Q controls - see section 4
SN = none
SP = pressure control (1 pressure transducer)
SF = force control (2 pressure transducers)
SL = force control (1 load cell)

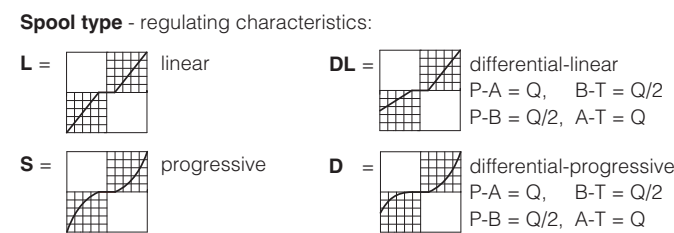
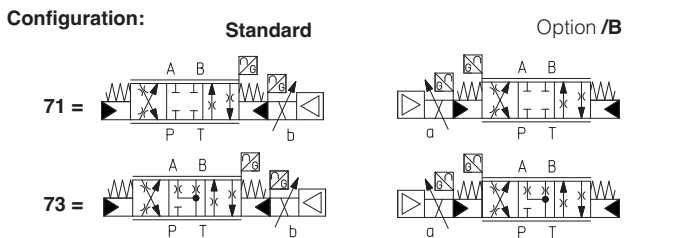
Fieldbus interfaces USB port always present:
NP = Not present (1) **EW** = POWERLINK
BC = CANopen **EH** = EtherCAT
BP = PROFIBUS DP **EI** = EtherNet/IP

Valve size ISO 4401:
1 = 10 **2** = 16 **4** = 25 **4M** = 27 **6** = 32 **8** = 35

Seals material, see sect. 5, 6:

- = NBR
- PE** = FKM
- BT** = HNBR

Series number



Hydraulic options, see section 10:

B = solenoid, integral electronics and position transducer at side of port B of the main stage (side A of pilot valve) (3)

D = internal drain

E = external pilot (through port X)

G = pressure reducing valve for piloting - standard for size 10

Electronic options, see sections 11

I = current reference input and monitor 4÷20 mA (omit for standard voltage reference input and monitor ±10 V)

Only for **SN (2)** :

F = fault signal

Q = enable signal

Z = double power supply (4), enable, fault and monitor signals - 12 pin connector

Only for **SP, SF, SL**:

C = current feedback for remote transducer(s)

Spool size 3 (L,S,D) 5 (L,DL,S,D) 5 (L,S,D)

DPZO-1	=	-	100	-
DPZO-2	=	160	250	-
DPZO-4	=	-	480	-
DPZO-4M	=	-	550	-
DPZO-6	=	-	-	640
DPZO-8	=	-	-	1200

Nominal flow (l/min) at Δp 10bar P-T

(1) LEB only in version SN-NP

(2) F, Q, Z options are standard for SP, SF, SL

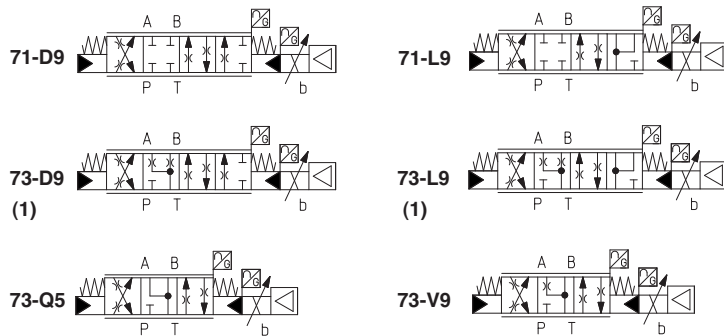
(3) In standard configuration the solenoid with integral electronics and position transducer are at side A of main stage (side B of pilot valve)

(4) double power supply only for LES

2 MODEL CODE for SPECIAL SPOOLS - refer to section 1 for valve model code and options

DPZO - **L** **ES** - **SN** - **NP** - **2** **71 - L9** / * / * / *

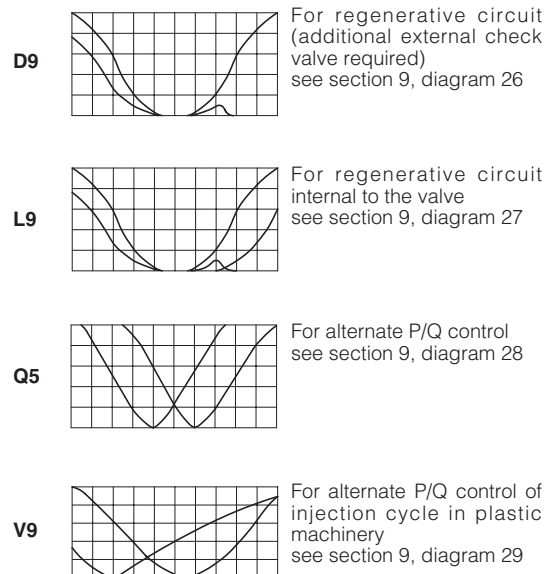
Configuration, spool type and size:



Spool size	D9	L9	V9	Q5
DPZO-1 =	100	-	100	100
DPZO-2 =	250	250	250	250
DPZO-4 =	480	-	480	480
DPZO-4M =	550	-	550	550
DPZO-6 =	-	-	640	-
DPZO-8 =	-	-	1200	-

Nominal flow (l/min) at Δp 10bar P-T

(1) do not use with alternated P/Q control (options SP, SF, SL)



3 GENERAL NOTES

DPZO-LEB, LES proportional valves are CE marked according to the applicable Directives (e.g. Immunity/Emission EMC Directive and Low Voltage Directive). Installation, wirings and start-up procedures must be performed according to the general prescriptions shown in table F003 and in the installation notes supplied with relevant components. The electrical signals of the valve (e.g. monitor signals) must not be directly used to activate safety functions, or components, as prescribed by the European standards (Safety requirements of fluid technology systems and components-hydraulics, EN-982).

! WARNING

To avoid overheating and possible damage of the electronic driver, the valves must be never energized without hydraulic supply to the pilot stage. In case of prolonged pauses of the valve operation during the machine cycle, it is always advisable to disable the driver (option /Q or /Z)

A safety fuse 2,5 A installed on 24Vdc power supply of each valve is always recommended, see also Power supply note at sections 11

4 ALTERNATED P/Q CONTROLS - only for **LES** with valve configuration **73**

S* options add the closed loop control of pressure (**SP**) or force (**SF** and **SL**) to the basic functions of proportional directional valves flow regulation. A dedicated algorithm alternates pressure (force) depending on the actual hydraulic system conditions.

An additional connector is available for transducers to be interfaced to the valve's driver (1 pressure transducer for SP, 2 pressure transducers for SF or 1 load cell for SL). Main 12 pin connector is the same as /Z option plus two analog signals specific for the pressure (force) control.

The alternated P/Q controls are specific for valve configuration 73, optional spools type Q5 and V9 recommended, see section 2

For detailed information and connector wiring of options SP, SF, SL see tech table **GS212**.

5 FIELDBUS - only for **LES**

Fieldbus allows the direct communication of the proportional valve with machine control unit for digital reference signal, diagnostics and settings of functional parameters. Analog reference signal remain available on the main connector for quick commissioning and maintenance. For detailed information about fieldbus features and specification see tech table **GS510**.

6 MAIN CHARACTERISTICS - based on mineral oil ISO VG 46 at 50 °C

Assembly position	Any position			
Subplate surface finishing	Roughness index, Ra 0,4 flatness ratio 0,01/100 (ISO 1101)			
MTTFd values according to EN ISO 13849	75 years, see technical table P007			
Ambient temperature range	standard = -20°C ÷ +60°C		/BT option = -40°C ÷ +60°C	
Storage temperature range	standard = -20°C ÷ +70°C		/BT option = -40°C ÷ +70°C	
Coil resistance R at 20°C	3 ÷ 3,3 Ω			
Max. solenoid current	2,6 A			
Max. power	50 Watt			
Insulation class	H (180°) Due to the occurring surface temperatures of the solenoid coils, the European standards ISO 13732-1 and EN 982 must be taken into account			
Protection degree to DIN EN60529	IP66/67 with mating connector			
Tropicalization	Tropical coating on electronics PCB			
Duty factor	Continuous rating (ED=100%)			
EMC, climate and mechanical load	See technical table G004			
Communication interface	USB Atos ASCII coding	CANopen EN50325-4 + DS408	PROFIBUS DP EN50170-2/IEC61158	EtherCAT, POWERLINK EtherNet/IP IEC 61158
Communication physical layer	not insulated USB 2.0 + USB OTG	optical insulated CAN ISO11898	optical insulated RS485	Fast Ethernet, insulated 100 Base TX

Valve model	DPZO-*-1	DPZO-*-2	DPZO-*-4	DPZO-*-4M	DPZO-*-6	DPZO-*-8
Pressure limits [bar]	ports P, A, B, X = 350; T = 250 (10 for option /D); Y = 10;					
Spool type	standard	L5, DL5, S5, D5	L3, S3, D3	L5, DL5, S5, D5		L5, S5, D5
	special	D9, V9, Q5		D9, L9, V9, Q5	D9, V9, Q5	V9
Nominal flow [l/min]						
(1) Δp = 10 bar	100	160	250	480	550	1200
Δp P-T Δp = 30 bar	160	270	430	830	950	2000
Max permissible flow [l/min]	180	400	550	1000	1100	3500
Piloting pressure [bar]	min. = 25; max = 350 (option /G advisable for pilot pressure > 200 bar)					
Piloting volume [cm³]	1,4	3,7	9,0	11,3	21,6	39,8
Piloting flow (2) [l/min]	1,7	3,7	6,8	8	14,4	20
Leakage Pilot [cm³/min]	100/300	100/300	200/500	200/600	900/2800	900/2800
	(3) Main stage [l/min]	0,15/0,5	0,2/0,6	0,3/1,0	0,3/1,0	1,0/3,0
Response time (4) [ms]	< 50	< 60	< 80	< 85	< 90	< 120
Hysteresis	≤ 0,1 [% of max regulation]					
Repeatability	± 0,1 [% of max regulation]					
Thermal drift	zero point displacement < 1% at ΔT = 40°C					

Notes: above performance data refer to valves coupled with Atos electronic drivers, see section 8.

(1) for different Δp, see section 9.2

(3) at p = 100/350 bar

(2) with step reference input signal 0 ÷ 100 %

(4) see detailed diagrams in section 9.3

7 SEALS AND HYDRAULIC FLUID - for other fluids not included in below table, consult our technical office

Seals, recommended fluid temperature	NBR seals (standard) = -20°C ÷ +60°C, with HFC hydraulic fluids = -20°C ÷ +50°C FKM seals (/PE option) = -20°C ÷ +80°C HNBR seals (/BT option) = -40°C ÷ +60°C, with HFC hydraulic fluids = -40°C ÷ +50°C		
Recommended viscosity	20 ÷ 100 mm²/s - max allowed range 15 ÷ 380 mm²/s		
Fluid contamination class	ISO 4406 class 20/18/15 NAS 1638 class 9, in line filters of 10 μm (β10 ≥75 recommended)		
Hydraulic fluid	Suitable seals type	Classification	Ref. Standard
Mineral oils	NBR, FKM, HNBR	HL, HLP, HLPD, HVL, HVLDP	DIN 51524
Flame resistant without water	FKM	HFDU, HFDR	ISO 12922
Flame resistant with water	NBR, HNBR	HFC	

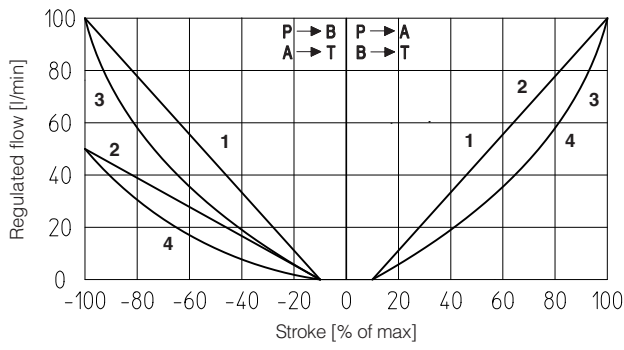
8 ELECTRONIC DRIVERS

Valve model	LEB	LES	LES-SP, SF, SL
Drivers model	E-RI-LEB-N	E-RI-LES-N	E-RI-LES-S
Type	Digital		
Format	Integral to valve		
Data sheet	GS208	GS210	GS212

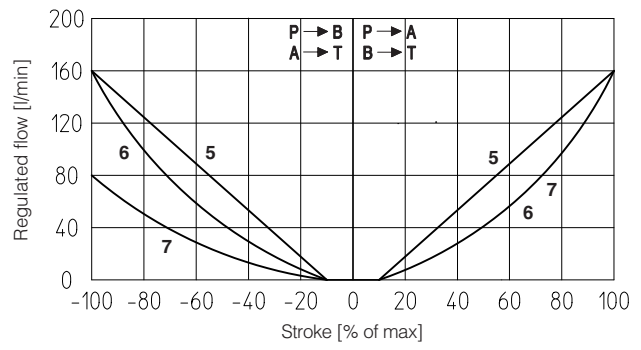
Note: for main and communication connector see sections 13, 14

9 DIAGRAMS (based on mineral oil ISO VG 46 at 50 °C)

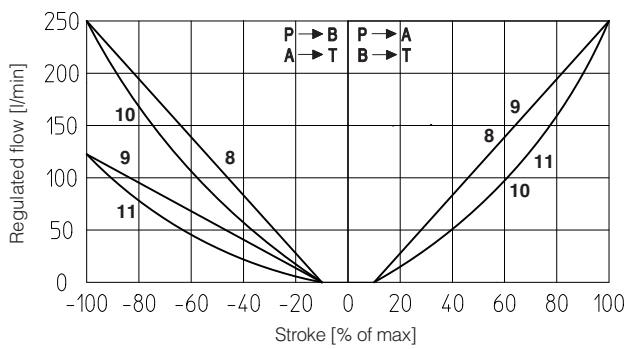
9.1 Regulation diagrams (values measure at Δp 10 bar P-T)



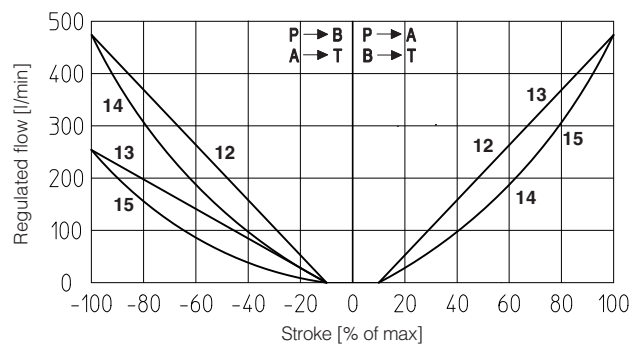
DPZO-1:
 1=L5 2 = DL5
 3=S5 4 = D5



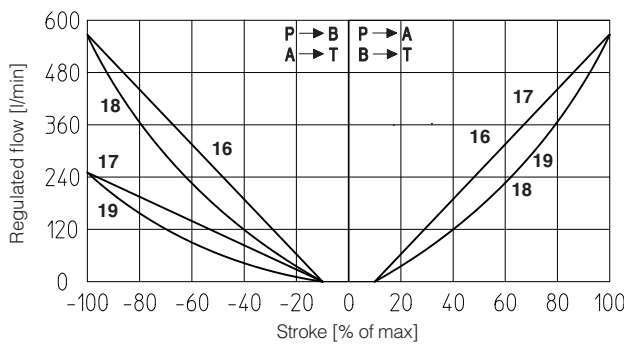
DPZO-2:
 5=L3 6 = S3
 7=D3



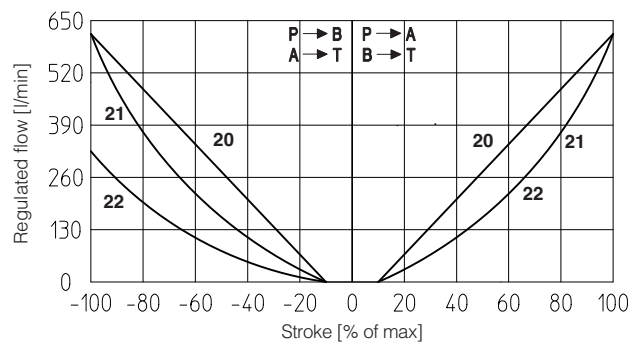
DPZO-2:
 8 = L5 9 = DL5
 10 = S5 11 = D5



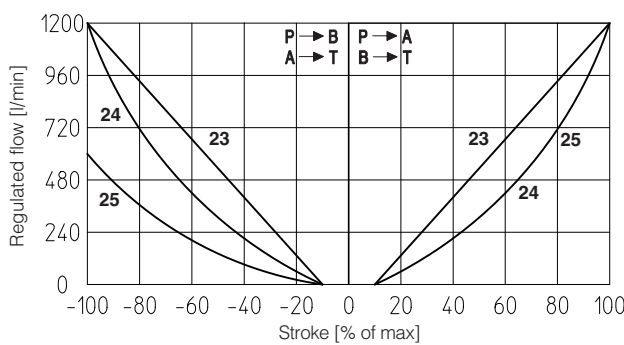
DPZO-4:
 12 = L5 13 = DL5
 14 = S5 15 = D5



DPZO-4M:
 16 = L5 17 = DL5
 18 = S5 19 = D5



DPZO-6:
 20 = L5 21 = S5
 22 = D5



DPZO-8:
 23 = L5 24 = S5
 25 = D5

Note:

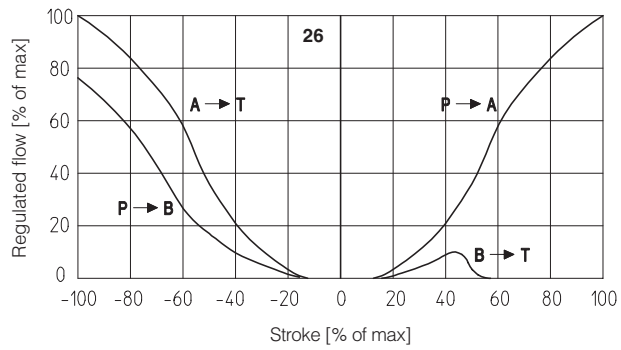
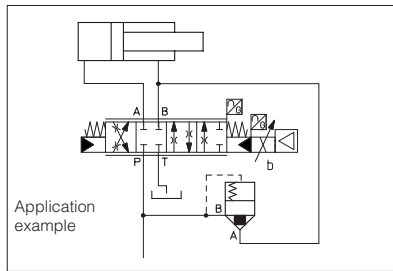
Hydraulic configuration vs. reference signal (standard and option /B)

Reference signal $\left. \begin{matrix} 0 \div +10 \text{ V} \\ 12 \div 20 \text{ mA} \end{matrix} \right\} \text{P} \rightarrow \text{A} / \text{B} \rightarrow \text{T}$

Reference signal $\left. \begin{matrix} 0 \div -10 \text{ V} \\ 12 \div 4 \text{ mA} \end{matrix} \right\} \text{P} \rightarrow \text{B} / \text{A} \rightarrow \text{T}$

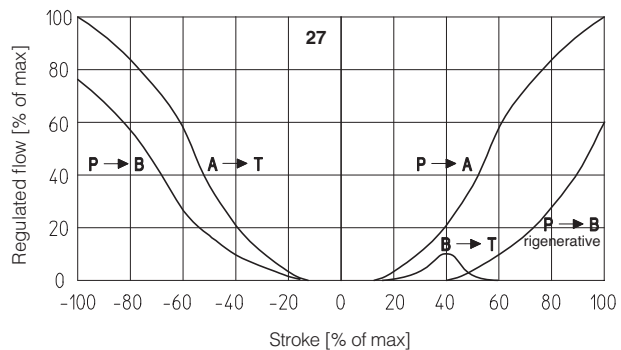
26 = differential - regenerative spool **D9**
(not available for valve size 32 and 35)

D9 spool type with a fourth position specific to regenerative circuit, performed by means of an additional external check valve.



27 = linear - internal regenerative spool **L9**
(available only for valve size 16)

L9 spool type with a fourth position specific to perform a regenerative circuit internal to the valve.

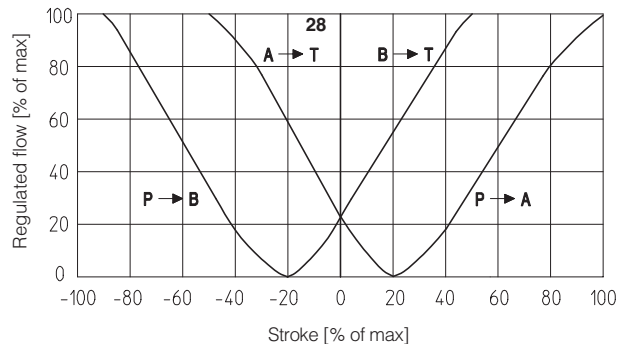


28 = linear spool **Q5**
(not available for valve size 32 and 35)

Q5 spool type is specific for alternate P/Q controls in combination with /S* option of digital integral drivers, (see tech. table **GS212**).

It allows to control the pressure in A port or B port and it provides a safety central position (A-T/B-T) to depressurize the actuator chambers.

The strong meter-in characteristic makes the spool suitable for both pressure control and motion regulations in several applications.

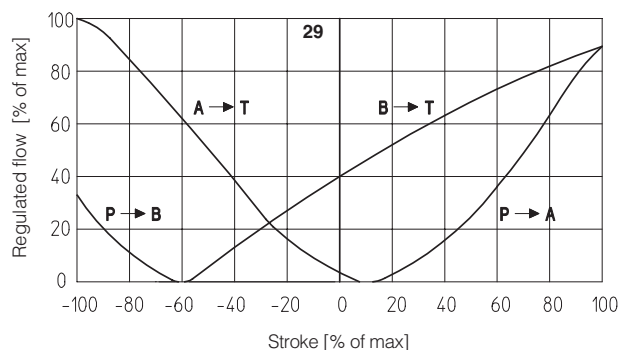


29 = differential - progressive spool **V9**

V9 spool type is specific for alternate P/Q controls in combination with S* option of digital integral drivers (see tech table **GS212**) or Z-ME-KZ/GI axis card (see tech table **G345**).

This spool is specially designed to manage the whole injection cycle in plastic machinery, thanks to the following specific features:

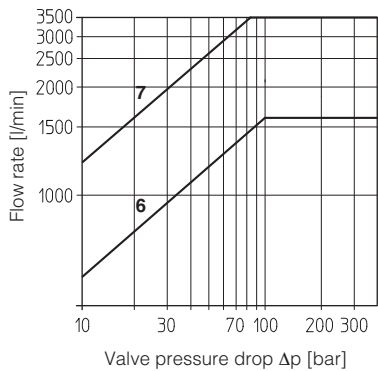
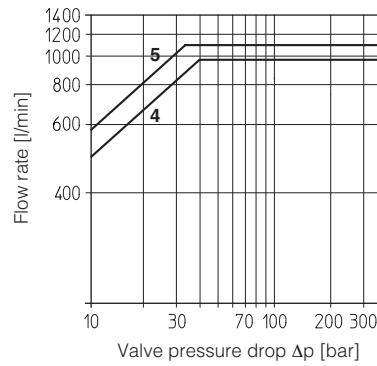
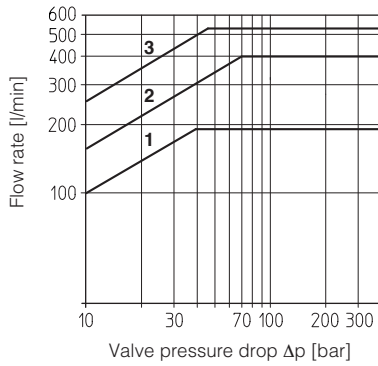
- strong meter-in characteristic to allow the pressure control in A port during the holding pressure (P-A) and the plasticizing (A-T) phases
- safety central position (A-T/B-T) to depressurize the actuator chambers
- large A-T and B-T flow capability, required during the plasticizing phase, to discharge big volumes from high differential injection cylinders with low pressure drops and permitting the contemporary oil suction from tank



9.2 Operating diagrams

Flow / Δp diagram

stated at 100% of spool stroke



DPZO-1:

1 = spools L5, S5, D5, DL5, D9, V9, Q5

DPZO-2:

2 = spools L3, S3, D3

3 = spools L5, S5, D5, DL5, D9, L9, V9, Q5

DPZO-4:

4 = spools L5, S5, D5, DL5, D9, V9, Q5

DPZO-4M:

5 = spools L5, S5, D5, DL5, D9, V9, Q5

DPZO-6:

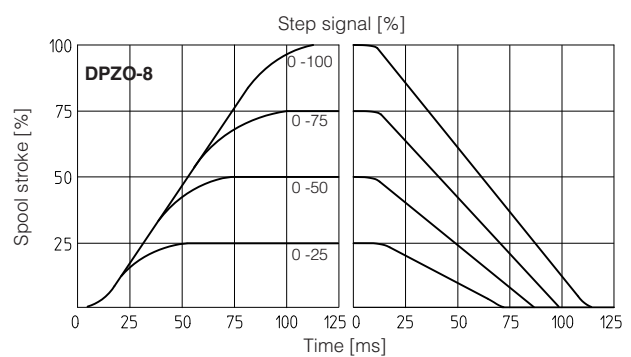
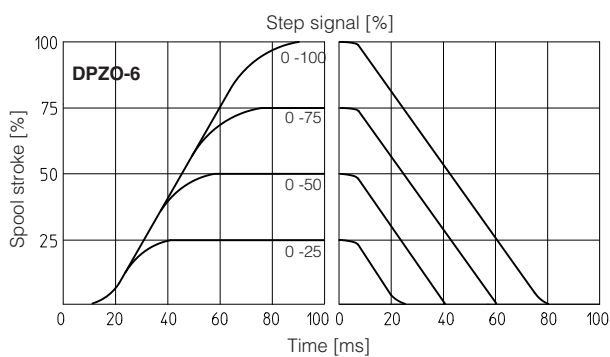
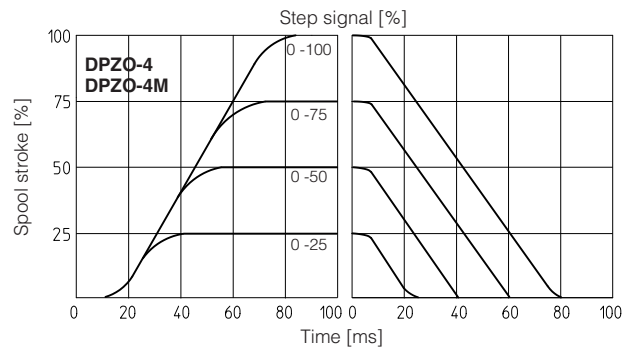
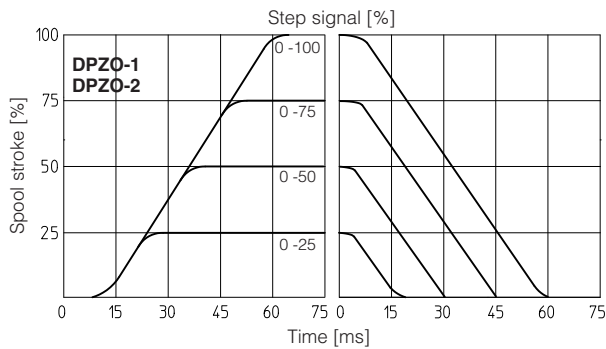
6 = L5, S5, D5, V9

DPZO-8:

7 = L5, S5, D5, V9

9.3 Response time

The response times in below diagrams are measured at different steps of the reference input signal. They have to be considered as average values. For the valves with digital electronics the dynamics performances can be optimized by setting the internal software parameters.



10 HYDRAULIC OPTIONS

10.1 Option /B

Solenoid, integral electronics and position transducer at side of port B of the main stage.
For hydraulic configuration vs reference signal, see section 9.1

10.2 Option /G

Pressure reducing valve ③ with fixed setting, installed between pilot valve and main body. Reduced pressure setting:

40 bar for DPZO-1 and DPZO-2

100 bar for DPZO-4(M), DPZO-6 and DPZO-8

It is advisable for valves with internal pilot in case of system pressure higher than 200 bar.

Pressure reducing valve ③ is standard for DPZO-1, for other sizes add /G option.

10.3 Pilot and drain configuration

The pilot / drain configuration can be modified as shown in the functional scheme here aside, for detailed view of plugs position, see section 16

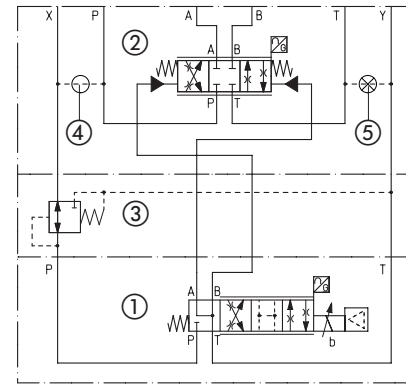
The valve's standard configuration provides internal pilot and external drain.

For different pilot / drain configuration select:

Option /E External pilot (through port X)

Option /D Internal drain (through port T)

FUNCTIONAL SCHEME - example of configuration 71



① Pilot valve

② Main stage

③ Pressure reducing valve

④ Plug to be added for external pilot trough port X

⑤ Plug to be removed for internal drain through port T

11 ELECTRONIC OPTIONS

Standard driver execution provides on the 7 pin main connector:

Power supply - 24 VDC must be appropriately stabilized or rectified and filtered; **2,5 A** fuse time lag is required in series to each driver power supply. Apply at least a 10000 μ F/40 V capacitance to single phase rectifiers or a 4700 μ F/40 V capacitance to three phase rectifiers

Reference input signal - analog differential input with ± 10 VDC nominal range (pin D, E), proportional to desired valve spool position

Monitor output signal - analog output signal proportional to the actual valve's spool position with ± 10 VDC nominal range

Note: a minimum booting time between 400 and 800 ms has to be considered from the driver energizing with the 24 Vdc power supply before the valve has been ready to operate. During this time the current to the valve coils is switched to zero.

11.1 Option /F

It provides a Fault output signal in place of the Monitor output signal, to indicate fault conditions of the driver (cable interruption of spool transducers or reference signal - for /I option): Fault presence corresponds to 0 VDC, normal working corresponds to 24 VDC

11.2 Option /I

It provides 4 \div 20 mA current reference and monitor signals, instead of the standard ± 10 V.

Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of ± 10 V or ± 20 mA.

It is normally used in case of long distance between the machine control unit and the valve or where the reference signal can be affected by electrical noise; the valve functioning is disabled in case of reference signal cable breakage.

11.3 Option /Q

To enable the driver, supply 24 VDC on pin C referred to pin B: Enable input signal allows to enable/disable the current supply to the solenoid, without removing the electrical power supply to the driver; it is used to maintain active the communication and the other driver functions when the valve has to be disabled. This condition does not comply with European Norms EN13849-1 (ex EN954-1).

11.4 Option /Z

It provides, on the 12 pin main connector, the following additional features:

Enable Input Signal

To enable the driver, supply 24 VDC on pin 3 referred to pin 2: Enable input signal allows to enable/disable the current supply to the solenoid, without removing the electrical power supply to the driver; it is used to maintain active the communication and the other driver functions when the valve has to be disabled. This condition does not comply with European Norms EN13849-1 (ex EN954-1).

Fault Output Signal

Fault output signal indicates fault conditions of the driver (solenoid short circuits/not connected, reference signal cable broken for 4 \div 20mA input, etc.). Fault presence corresponds to 0 VDC, normal working corresponds to 24 VDC (pin 11 referred to pin 2): Fault status is not affected by the Enable input signal

Power supply for driver's logics and communication - only for LES

Separate power supply (pin 9,10) allow to cut solenoid power supply (pin 1,2) while maintaining active diagnostics, USB and fieldbus communication. A safety fuse is required in series to each driver power supply: 500 mA fast fuse.

11.5 Options /C - only for SP, SF, SL

Option /C is available to connect pressure (force) transducers with 4 \div 20 mA current output signal, instead of the standard ± 10 V.

Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of ± 10 V or ± 20 mA.

11.6 Possible combined options

For SN: /F, /I, /Q and /Z

For SP, SF, SL: /C

12 ELECTRONIC CONNECTIONS AND LEADS

12.1 Main connector signals - 7 pin - standard, /F and /Q options (A1)

PIN	Standard	/Q	/F	TECHNICAL SPECIFICATIONS	NOTES
A	V+			Power supply 24 Vdc Rectified and filtered: $V_{RMS} = 20 \div 32 V_{MAX}$ (ripple max 10 % V_{PP})	Input - power supply
B	V0			Power supply 0 Vdc	Gnd - power supply
C	AGND		AGND	Analog ground	Gnd - analog signal
		ENABLE		Enable (24 Vdc) or disable (0 Vdc) the valve, referred to V0	Input - on/off signal
D	Q_INPUT+			Flow reference input signal: ± 10 Vdc / ± 20 mA maximum range Defaults are ± 10 Vdc for standard and $4 \div 20$ mA for /I option	Input - analog signal Software selectable
E	INPUT-			Negative reference input signal for Q_INPUT+	Input - analog signal
F	Q_MONITOR referred to: AGND V0			Flow monitor output signal: ± 10 Vdc / ± 20 mA maximum range Defaults are ± 10 Vdc for standard and $4 \div 20$ mA for /I option	Output - analog signal Software selectable
			FAULT	Fault (0 Vdc) or normal working (24 Vdc)	Output - on/off signal
G	EARTH			Internally connected to the driver housing	

12.2 Main connector signals - 12 pin - /Z option and SP, SF, SL (A2)

PIN	LEB-SN /Z	LES-SN /Z	LES-SP, SF, SL Fieldbus NP		TECHNICAL SPECIFICATIONS	NOTES
1	V+				Power supply 24 Vdc Rectified and filtered: $V_{RMS} = 20 \div 32 V_{MAX}$ (ripple max 10 % V_{PP})	Input - power supply
2	V0				Power supply 0 Vdc	Gnd - power supply
3	ENABLE referred to: V0 VL0		VL0	V0	Enable (24 Vdc) or disable (0 Vdc) the valve	Input - on/off signal
4	Q_INPUT+				Flow reference input signal: ± 10 Vdc / ± 20 mA maximum range Defaults are ± 10 Vdc for standard and $4 \div 20$ mA for /I option	Input - analog signal Software selectable
5	INPUT-				Negative reference input signal for Q_INPUT+ and F_INPUT+	Input - analog signal
6	Q_MONITOR referred to: AGND VL0		VL0	V0	Flow monitor output signal: ± 10 Vdc / ± 20 mA maximum range Defaults are ± 10 Vdc for standard and $4 \div 20$ mA for /I option	Output - analog signal Software selectable
7	AGND				Analog ground	Gnd - analog signal
	NC				Do not connect	
8	R_ENABLE				Repeat enable, output repeter signal of enable input, referred to V0	Output - on/off signal
	NC				Do not connect	
9			F_INPUT+		Pressure/Force reference input signal: ± 10 Vdc / ± 20 mA maximum range Defaults are ± 10 Vdc for standard and $4 \div 20$ mA for /I option	Input - analog signal Software selectable
	NC				Do not connect	
10			F_MONITOR referred to: VL0 V0		Pressure/Force monitor output signal: ± 10 Vdc / ± 20 mA maximum range Defaults are ± 10 Vdc for standard and $4 \div 20$ mA for /I option	Output - analog signal Software selectable
	NC				Do not connect	
11	VL+				Power supply 24 Vdc for driver's logic and communication	Input - power supply
			D_IN0		Multiple pressure/force PID selection, referred to V0	Input - analog signal
12	NC				Do not connect	
	VL0				Power supply 0 Vdc for driver's logic and communication	Gnd - power supply
13			D_IN1		Multiple pressure/force PID selection (not available for SF), referred to V0	Input - on/off signal
	FAULT referred to: V0 VL0		VL0	VL0	Fault (0 Vdc) or normal working (24 Vdc)	Output - on/off signal
PE	EARTH				Internally connected to the driver housing	

Note: do not disconnect VL0 before VL+ when the driver is connected to PC USB port

12.3 Communications connectors (B) - (C)

(B) USB connector - M12 - 5 pin always present		
PIN	SIGNAL	TECHNICAL SPECIFICATION (1)
1	+5V_USB	Supply for external USB Flash Drive
2	ID	USB Flash Drive identification
3	GND_USB	Signal zero data line
4	D-	Data line -
5	D+	Data line +

(C1) (C2) BP fieldbus execution, connector - M12 - 5 pin		
PIN	SIGNAL	TECHNICAL SPECIFICATION (1)
1	+5V	Termination supply signal
2	LINE-A	Bus line (high)
3	DGND	Data line and termination signal zero
4	LINE-B	Bus line (low)
5	SHIELD	

Notes: (1) shield connection on connector's housing is recommended

(C1) (C2) BC fieldbus execution, connector - M12 - 5 pin		
PIN	SIGNAL	TECHNICAL SPECIFICATION (1)
1	CAN_SHLD	Shield
2	not used	(C1) - (C2) pass-through connection (2)
3	CAN_GND	Signal zero data line
4	CAN_H	Bus line (high)
5	CAN_L	Bus line (low)

(C1) (C2) EH, EW, EI fieldbus execution, connector - M12 - 4 pin		
PIN	SIGNAL	TECHNICAL SPECIFICATION (1)
1	TX+	Transmitter
2	RX+	Receiver
3	TX-	Transmitter
4	RX-	Receiver
Housing	SHIELD	

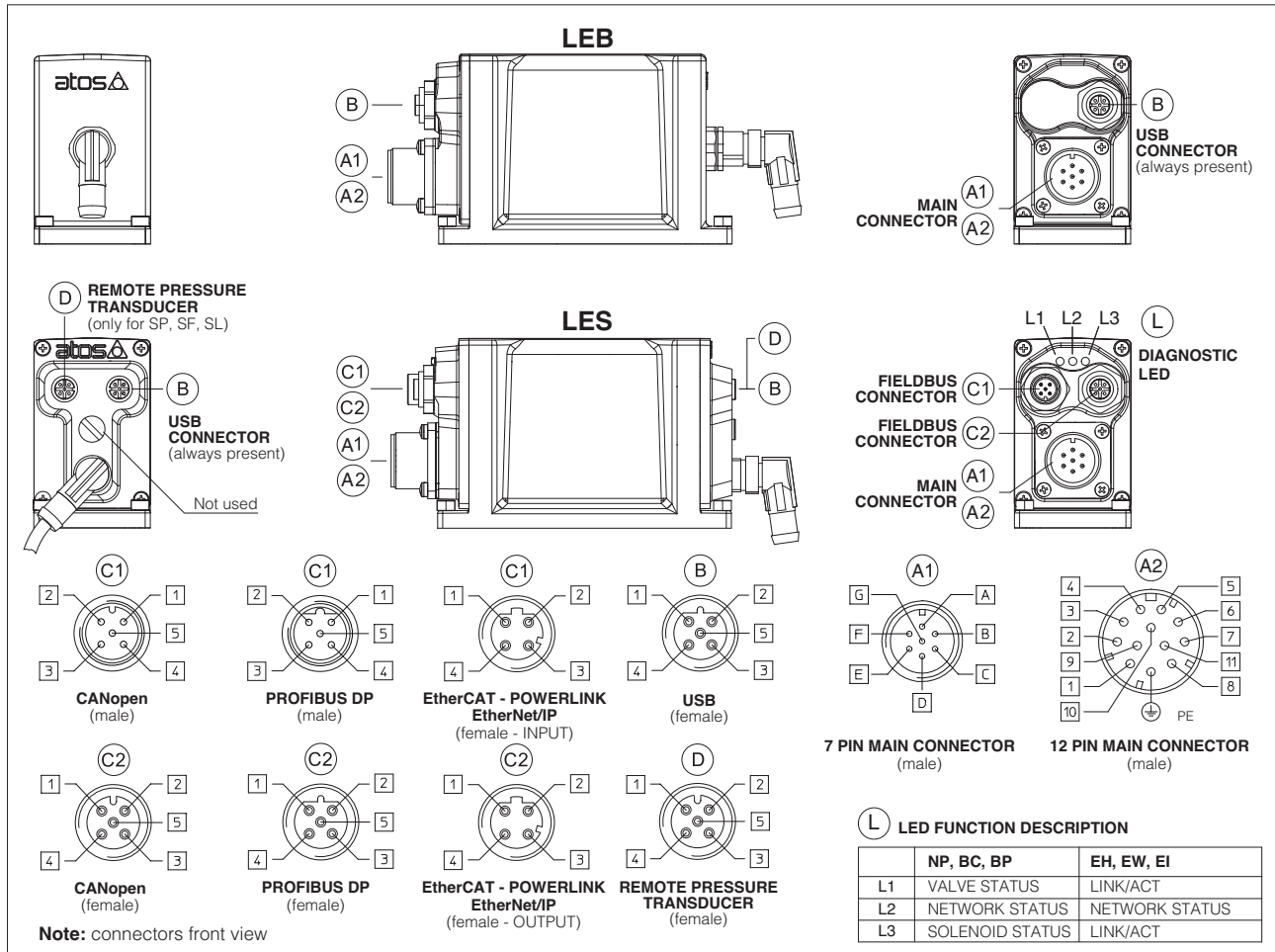
(2): pin 2 can be fed with external +5V supply of CAN interface

12.4 Remote pressure/force transducer connector - M12 - 5 pin - only for SP, SF, SL (D)

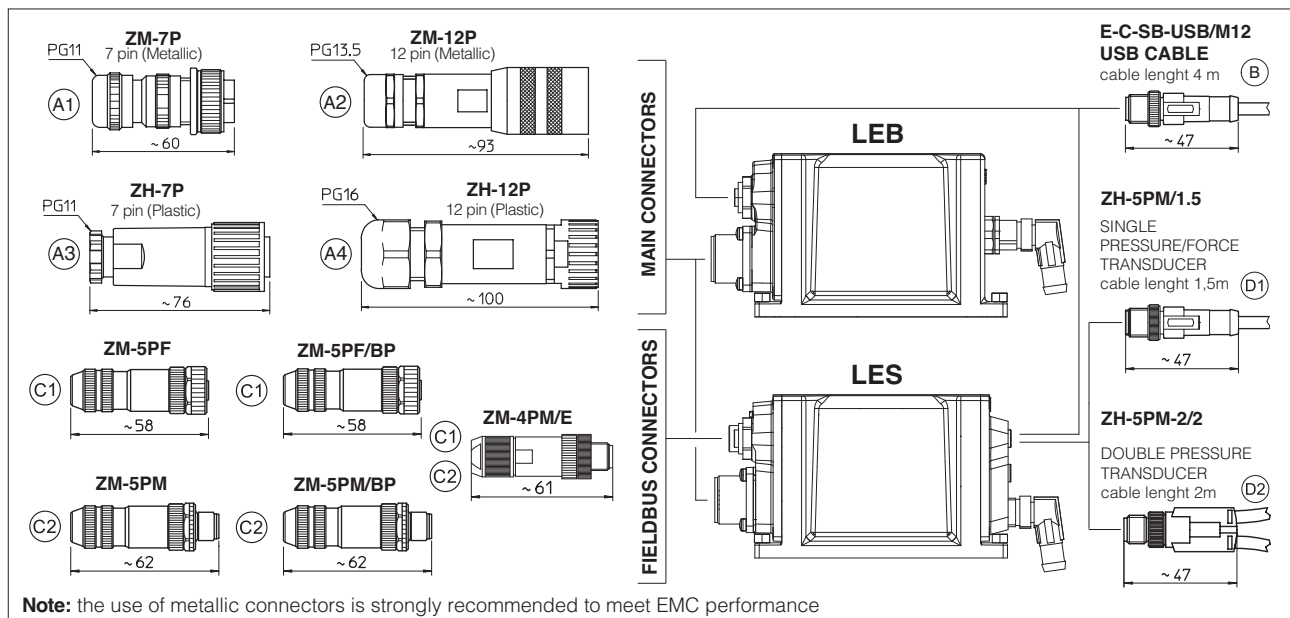
PIN	SIGNAL	TECHNICAL SPECIFICATION	Single transducer (1)		Double transducers (1)	
			Voltage	Current	Voltage	Current
1	VF +24V	Power supply +24Vdc	Connect	Connect	Connect	Connect
2	TR1	1st signal transducer: ± 10 Vdc / ± 20 mA maximum range, software selectable Defaults are ± 10 Vdc for standard and $4 \div 20$ mA for /C option	Connect	Connect	Connect	Connect
3	AGND	Common GND for transducer power and signals	Connect	/	Connect	/
4	TR2	2nd signal transducer: ± 10 Vdc / ± 20 mA maximum range, software selectable Defaults are ± 10 Vdc for standard and $4 \div 20$ mA for /C option	/	/	Connect	Connect
5	NC	Not connect	/	/	/	/

Note (1) single/double transducer configuration is software selectable

12.5 Connections layout



13 CONNECTORS



14 MODEL CODES OF MAIN CONNECTORS AND COMMUNICATION CONNECTORS - to be ordered separately

VALVE VERSION	LEB LES	LEB /Z LES /Z	BC - CANopen	BP - PROFIBUS DP	EH - EtherCat EW - POWERLINK EI - EtherNet/IP	P/Q controls SP, SL, SF
CONNECTOR CODE	ZM-7P (A1)	ZM-12P (A2)	ZM-5PF (C1)	ZM-5PF/BP (C1)	ZM-4PM/E (C1)	ZH-5PM/1.5 (1) (D1)
	ZH-7P (A3)	ZH-12P (A4)	ZM-5PM (C2)	ZM-5PM/BP (C2)	ZM-4PM/E (C2)	ZH-5PM-2/2 (2) (D2)
PROTECTION DEGREE	IP67					
DATA SHEET	GS208, GS210, GS212, K500					

only for LES

(1) only for SP or SL

(2) only for SF

15 PROGRAMMING TOOLS - see table **GS500**

Valve's functional parameters and configurations, can be easily set and optimized using Atos E-SW programming software connected via USB port to the digital driver. For fieldbus versions, the software permits valve's parameterization through USB port also if the driver is connected to the central machine unit via fieldbus.

The software is available in different versions according to the driver's options:

E-SW-BASIC support: NP (USB) PS (Serial) IR (Infrared)

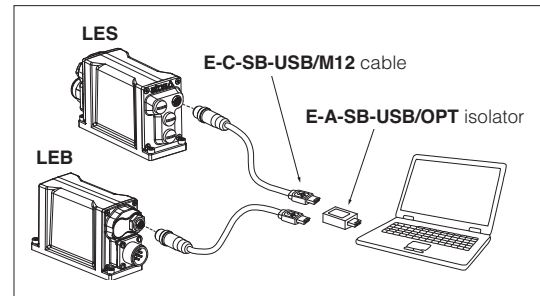
E-SW-FIELDBUS support: BC (CANopen) BP (PROFIBUS DP) EH (EtherCAT)
EW (POWERLINK) EI (EtherNet/IP)

E-SW-*/PQ support: valves with SP, SF, SL alternated control (e.g. E-SW-BASIC/PQ)

WARNING: drivers USB port is not isolated!

The use of isolator adapter is highly recommended for PC protection (see table **GS500**)

USB connection



16 PLUGS LOCATION FOR PILOT/DRAIN CHANNELS

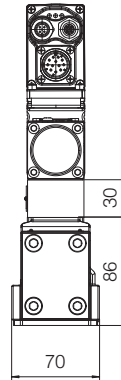
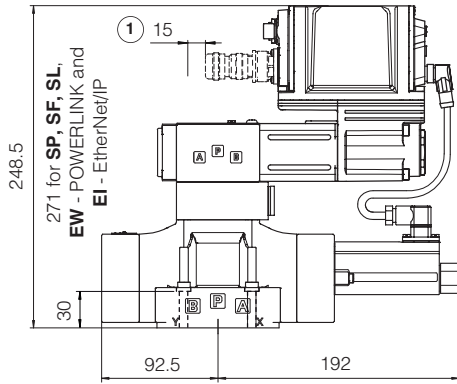
Depending on the position of internal plugs, different pilot/drain configurations can be obtained as shown below.

To modify the pilot/drain configuration, proper plugs must only be interchanged. The plugs have to be sealed using loctite 270.

Standard valves configuration provides internal pilot and external drain

<p>DPZO-1 Pilot channels</p>	<p>Drain channels</p>	<p>Internal piloting: blinded plug SP-X300F ① in X; External piloting: blinded plug SP-X300F ② in Pp; Internal drain: blinded plug SP-X300F ③ in Y; External drain: blinded plug SP-X300F ④ in Dr.</p>
<p>DPZO-2 Pilot channels</p>	<p>Drain channels</p>	<p>Internal piloting: Without blinded plug SP-X300F ①; External piloting: Add blinded plug SP-X300F ①; Internal drain: Without blinded plug SP-X300F ②; External drain: Add blinded plug SP-X300F ②.</p>
<p>DPZO-4 Pilot channels</p>	<p>Drain channels</p>	<p>Internal piloting: Without blinded plug SP-X500F ①; External piloting: Add blinded plug SP-X500F ①; Internal drain: Without blinded plug SP-X300F ②; External drain: Add blinded plug SP-X300F ②.</p>
<p>DPZO-6 Pilot channels</p>	<p>Drain channels</p>	<p>Internal piloting: Without plug ①; External piloting: Add DIN-908 M16x1,5 in pos ①; Internal drain: Without blinded plug SP-X300F ③; External drain: Add blinded plug SP-X300F ③.</p>
<p>DPZO-8 Pilot channels</p>	<p>Drain channels</p>	<p>Internal piloting: Without plug ①; External piloting: Add NPTF 1/8 in pos ①; plug NPTF 1/8 in pos ②; Internal drain: Without plug NPTF 1/8 in pos ③; Add plug NPTF 1/8 in pos ④; External drain: Add plug NPTF 1/8 in pos ③.</p>

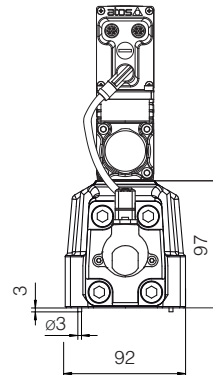
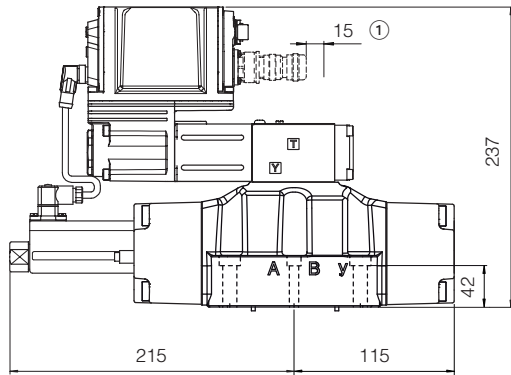
DPZO-LEB-*-1
DPZO-LES-*-1



ISO 4401: 2005
Mounting surface: 4401-05-05-0-05
(see table P005)
Fastening bolts:
4 socket head screws M6x40 class 12.9
Tightening torque = 15 Nm
Seals: 5 OR 2050; 2 OR 108
Diameter of ports A, B, P, T: $\varnothing = 11$ mm;
Diameter of ports X, Y: $\varnothing = 5$ mm;

Mass 9,5 kg

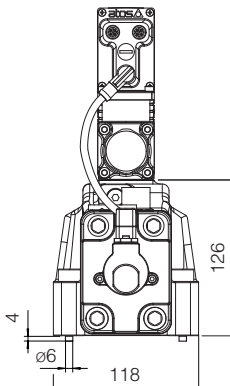
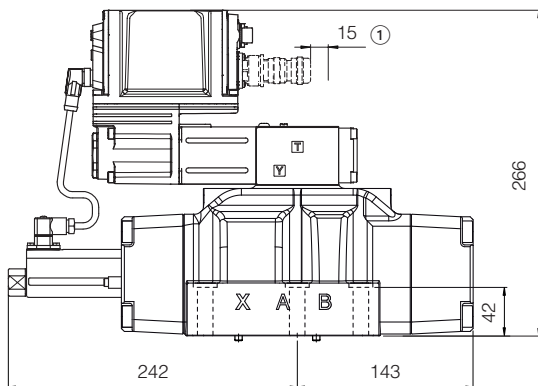
DPZO-LEB-*-2
DPZO-LES-*-2



ISO 4401: 2005
Mounting surface: 4401-07-07-0-05
(see table P005)
Fastening bolts:
4 socket head screws M10x50 class 12.9
Tightening torque = 70 Nm
2 socket head screws M6x45 class 12.9
Tightening torque = 15 Nm
Seals: 4 OR 130; 2 OR 2043
Diameter of ports A, B, P, T: $\varnothing = 20$ mm;
Diameter of ports X, Y: $\varnothing = 7$ mm;

Mass 14 kg

DPZO-LEB-*-4
DPZO-LES-*-4



ISO 4401: 2005
Mounting surface: 4401-08-08-0-05
(see table P005)
Fastening bolts:
6 socket head screws M12x60 class 12.9
Tightening torque = 125 Nm

DPZO-4
Seals: 4 OR 4112; 2 OR 3056
Diameter of ports A, B, P, T: $\varnothing = 24$ mm;
Diameter of ports X, Y: $\varnothing = 7$ mm;

DPZO-4M
Seals: 4 OR 4131; 2 OR 3056
Diameter of ports A, B, P, T: $\varnothing = 32$ mm;
Diameter of ports X, Y: $\varnothing = 7$ mm;

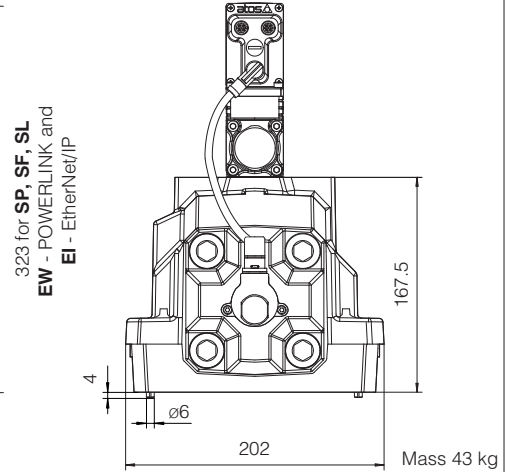
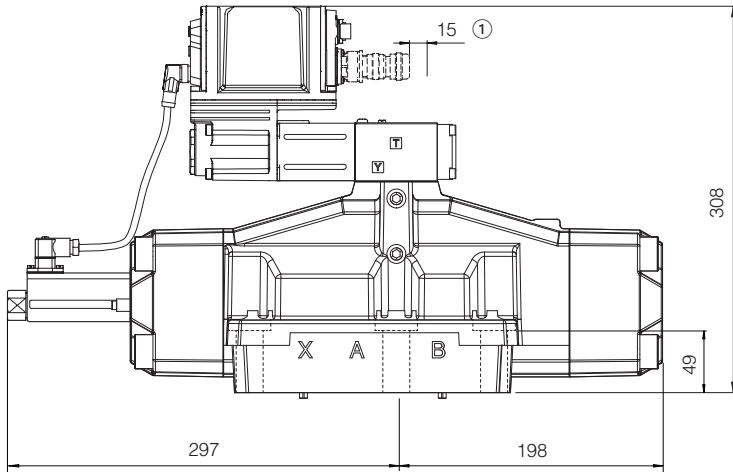
Mass 19 kg

① = Space to remove the 7 or 12 pin main connector. For main and communication connectors see section 13, 14

Note: the overall height is increased by 40 mm for /G option (0,9 kg).
For option /B the proportional solenoid, the position transducer and the electronics are at side of port B of the main stage.

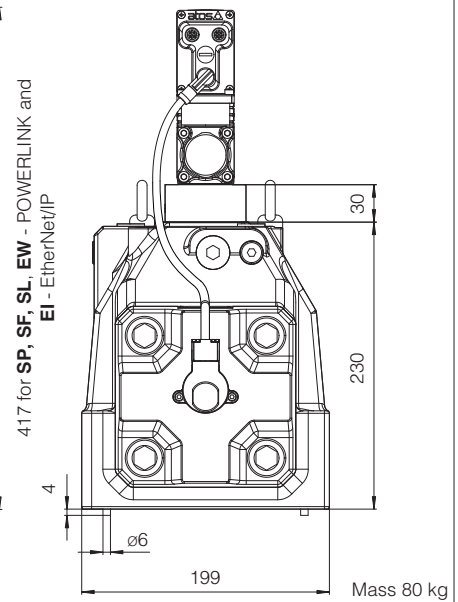
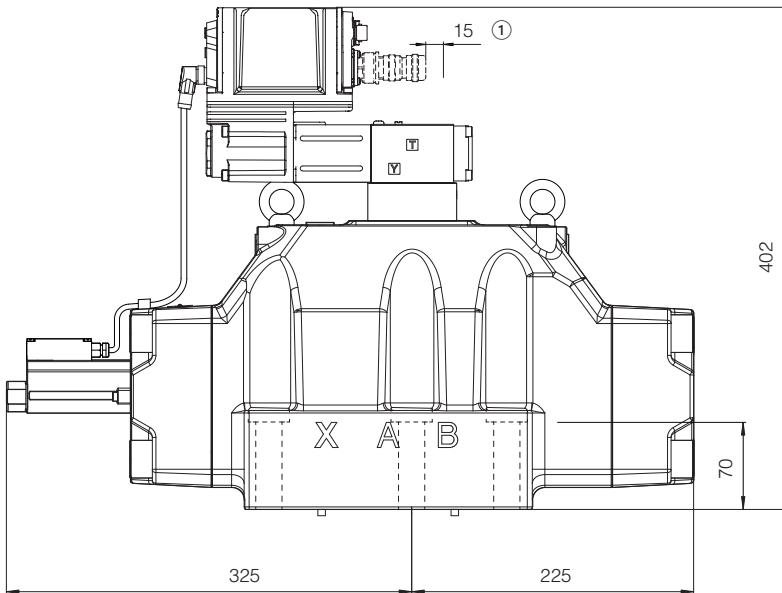
DPZO-LEB-*-6
DPZO-LES-*-6

ISO 4401: 2005
Mounting surface: 4401-10-09-0-05
 (see table P005)
 Fastening bolts:
 6 socket head screws M20x90 class 12.9
 Tightening torque = 600 Nm
 Diameter of ports A, B, P, T: $\varnothing = 34$ mm;
 Diameter of ports X, Y: $\varnothing = 7$ mm;
 Seals: 4 OR 144, 2 OR 3056



DPZO-LEB-*-8
DPZO-LES-*-8

ISO 4401: 2005
Mounting surface: 4401-10-09-0-05
 (see table P005)
 Fastening bolts:
 6 socket head screws M20x100 class 12.9
 Tightening torque = 600 Nm
 Diameter of ports A, B, P, T: $\varnothing = 50$ mm;
 Diameter of ports X, Y: $\varnothing = 9$ mm;
 Seals: 4 OR 156, 2 OR 3056



① = Space to remove the 7 or 12 pin main connector. For main and communication connectors see section 13, 14

Note: the overall height is increased by 40 mm for /G option (0,9 kg).
 For option /B the proportional solenoid, the position transducer and the electronics are at side of port B of the main stage.