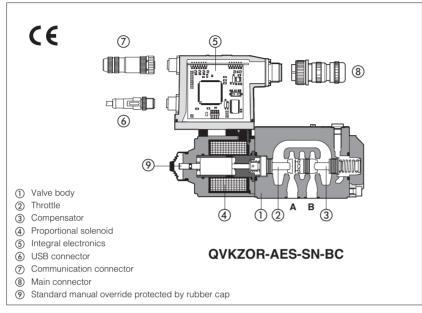


# **Proportional flow valves**

digital, pressure compensated, direct operated, open loop



# QVHZO-A, QVHZO-AEB, QVHZO-AES QVKZOR-A, QVKZOR-AEB, QVKZOR-AES

Pressure compensated, proportional flow control valves, direct operated, without position transducer for open loop flow regulations.

#### Executions:

- A without integral driver, to be coupled with separated drivers, see section 2.
- AEB with basic integral digital electronic driver, analog reference signals and USB port for software functional parameters setting
- AES with full integral digital electronic driver and fieldbus interface for functional parameters setting, reference signals and real-time diagnostics.

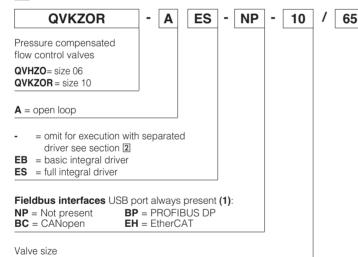
The integral digital electronic driver performs the valve's hydraulic regulation according to the reference signal and assures valve-to-valve interchangeability thanks to the factory presetting.

Sizes: 06 and 10

Max flow: up to 45 and 90 l/min

Max pressure: 210 bar

# 1 MODEL CODE



Max regulated flow:

QVHZO:	QVKZOR:		
3 = 3,51/min	<b>36</b> = 35 l/min	<b>65</b> =65 l/mir	1
<b>12</b> = 12 l/min	<b>45</b> = 45 l/min	<b>90</b> =90 I/mir	٦

**06**= ISO 4401, size 06 **10** = ISO 4401, size 10

**18** = 18 l/min

(1) Omit for A execution; AEB available only in version NP; AES available only in version BC, BP, EH

# \* / \* \*\* / \* Seals material, see sec. 5, 6: - = NBR Series number PE = FKM BT = HNBR Coil voltage only for A - see section : - = standard coil for 24Voc Atos drivers 6 = optional coil for 12Voc Atos drivers

18 = optional coil for low current drivers

Hydraulic options - see sect. 9:

**D** = quick venting of port B

Hand lever options, only for QVHZO-A - see sect. 10:

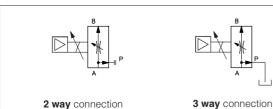
**MO** = horizontal hand lever

**MV** = vertical hand lever

Electronic options, only for AEB, AES - see sect. 111:

- **C** = current feedback 4÷20 mA for remote transducer, only in combination with option **W**
- I = current reference input 4÷20 mA
  - (omit for standard voltage reference input ±10 V)
- a = enable signal
- Z = double power supply, enable, fault and monitor signals - 12 pin connector
- W = Power limitation function 12 pin connector

#### Hydraulic symbols (2)



The valves can be used in 2 or 3 way connection, depending to the application requirements.

In 2 way the P port must not be connected (blocked)

In **3 way** the P port has to be connected to tank or to other user lines The port T must be always not connected (blocked)

For application examples of 2 and 3 way connections, see section 8

# 2 ELECTRONIC DRIVERS

Valve model		A						AEB	AES
Drivers model	E-MI-AC-01F	E-BM-AC-01F	E-ME-AC-01F	E-RP-AC-01F	E-MI-AS-IR	E-BM-AS-PS	E-BM-AES	E-RI-AEB	E-RI-AES
Туре		Analog				Digital			
Format	plug-in to solenoid	DIN 43700 UNDECAL	EUROCARD	sealed and rugged box	plug-in to solenoid	DIN-rail panel		Integral	to valve
Data sheet	G010	G025	G035	G100	G020	G030	GS050	GS	115

Note: For main and communication connector see sections [3] [4]

# 3 GENERAL NOTES

QVHZO-A\* and QVKZOR-A\* proportional valves are CE marked according to the applicable Directives (e.g. Immunity/Emission EMC Directive and Low Voltage Directive). Installation, wirings and start-up procedures must be performed according to the general prescriptions shown in table F003 and in the installation notes supplied with relevant components.

# 4 FIELDBUS - only for AES

Fieldbus allows valve direct communication with machine control unit for digital reference, valve diagnostics and settings. These execution allow to operate the valves through fieldbus or analog signals available on the main connector. For detailed information about fieldbus features and specification see tech table **GS510**.

# 5 MAIN CHARACTERISTICS - based on mineral oil ISO VG 46 at 50 °C

Assembly position	Any position	Any position						
Subplate surface finishing	Roughness inde	ex, Ra 0,4	4 flatnes	s ratio 0,01/100	(ISO 1101)			
MTTFd valves according to EN ISO 13849	150 years, see t	technical	table P	007				
Ambient temperature range	A: sta	ndard =	-20°C ÷	+70°C,	/BT option = -4	10°C ÷ -	+60°C	
	AEB, AES: sta	ndard =	-20°C ÷	- +60°C,	/BT option = -4	10°C ÷ -	+60°C	
Storage temperature range	A: sta	ndard =	-20°C -	- +80°C,	/BT option = -4	10°C ÷ -	+70°C	
	AEB, AES: sta	ndard =	-20°C -	- +70°C,	/BT option = -4	10°C ÷ -	+70°C	
Coil code		QVI	-IZO			QVK	ZOR	
	standard	optio	n /6	option /18	standard	opti	on /6	option /18
Coil resistance R at 20°C	3 ÷ 3,3 Ω	2 ÷ 2	2,2 Ω	13 ÷ 13,4 Ω	3,8 ÷ 4,1 Ω	2,2 ÷	2,4 Ω	12 ÷ 12,5 Ω
Max. solenoid current	2,2 A	2,7	5 A	1,2 A	2,6 A	3,2	25 A	1,2 A
Max. power	<b>A</b> = 30\	N	AEB, A	<b>ES</b> = 50W	<b>A</b> = 35V	V	AEB, AE	<b>S</b> = 50W
Insulation class	` '		_	rface temperatu e taken into acc	res of the solenoi ount	id coils,	the Euro	pean standards
Protection degree to DIN EN60529	IP66/67 with ma	ating con	nectors					
Tropicalization	Tropical coating	g on elec	tronics I	PCB				
Duty factor	Continuous ratir	ng (ED=	100%)					
EMC, climate and mechanical load	See technical table G004							
Communication interface	USB Atos ASCII codi		CANop EN5032	en 25-4 + DS408	PROFIBUS DP EN50170-2/IEC	61158	EtherCAT IEC 61158	
Communication physical layer	not insulated USB 2.0 + USB			insulated O11898	optical insulated RS485	b	Fast Eth 100 Bas	ernet, insulated se TX

Valve model		QVHZO					QVKZOR	
Max regulated	flow [I/min]	3,5	12	18	35	45	65	90
Min regulated	Min regulated flow [cm³/min]		20	30	50	60	85	100
Regulating $\Delta p$	[bar]	4	4 - 6		10 - 12		6 - 8	10 - 12
Max flow on po	Max flow on port A [I/min]		40		50	55	70	100
Max pressure	[bar]	210						
Response time	0÷100% step signal [ms]	30				45		
Hysteresis [% of the regulated max flow]		≤5						
Linearity	[% of the regulated max flow]	≤3						
Repeatability	[% of the regulated max flow]	≤1						

Notes: above performance data refer to valves coupled with Atos electronic drivers, see section 2

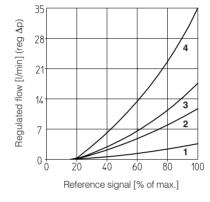
# 6 SEALS AND HYDRAULIC FLUID - for other fluids not included in below table, consult our technical office

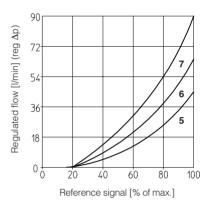
Seals, recommended fluid temperature	NBR seals (standard) = $-20^{\circ}$ C ÷ $+60^{\circ}$ C, with HFC hydraulic fluids = $-20^{\circ}$ C ÷ $+50^{\circ}$ C FKM seals (/PE option) = $-20^{\circ}$ C ÷ $+80^{\circ}$ C HNBR seals (/BT option) = $-40^{\circ}$ C ÷ $+60^{\circ}$ C, with HFC hydraulic fluids = $-40^{\circ}$ C ÷ $+50^{\circ}$ C				
Recommended viscosity	20÷100 mm²/s - max allowed range 15 ÷ 380 mm²/s				
Fluid contamination class	ISO 4406 class 20/18/15 NAS 1638 class 9, in line filters of 10 μm (β10 ≥75 recommended)				
Hydraulic fluid	Suitable seals type	Classification	Ref. Standard		
Mineral oils	NBR, FKM, HNBR	HL, HLP, HLPD, HVLP, HVLPD	DIN 51524		
Flame resistant without water	FKM	HFDU, HFDR	100 10000		
Flame resistant with water	NBR, HNBR	HFC	ISO 12922		

# 7 DIAGRAMS - based on mineral oil ISO VG 46 at 50 °C

# 7.1 Regulation diagrams

- 1 = QVHZO-\*-06/3
- 2 = QVHZO-\*-06/12
- 3 = QVHZO-\*-06/18 4 = QVHZO-\*-06/36
- **5** = QVHZO-\*-06**/45**
- 6 = QVKZOR-\*-10/65 7 = QVKZOR-\*-10/90

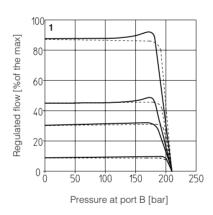


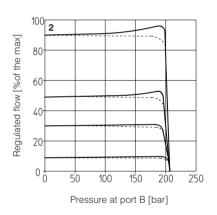


# **7.2 Regulated flow/outlet pressure diagrams** with inlet pressure = 210 bar

- 1 = QVHZO
- 2 = QVKZOR

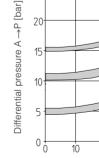
Dotted line for 3-way versions





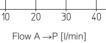
#### Flow A →P/∆p diagrams 7.3 3-way configuration

- 1 = QVHZO-\*-06/3 QVHZO-\*-06/12 2 = QVHZO-\*-06/18 QVHZO-\*-06/36 3 = QVHZO-\*-06/45 4 = QVKZOR-\*-10/65 5 = QVKZOR-\*-10/90



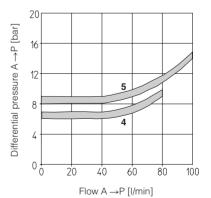
25

20

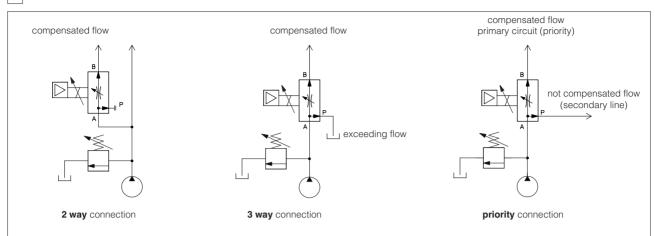


50

3



# 8 APPLICATIONS AND CONNECTIONS



#### 2 way connection

The 2 way connection is normally used to control the flow in one part of the hydraulic circuit or to regulate the speed of a specific actuator. The metered flow in the controlled line is kept constant, independently to the load variations

If the valve is directly installed on the pump main line, the exceeding flow is returned to tank though the pressure relief valve.

#### 3 way connection

The 3 way connection is normally used when the valve directly controls the pump flow (main line)

The metered flow in the controlled line is kept constant, independently to the load variations

The exceeding flow (not metered by the valve) it is returned to tank trough the valve P port = T line (3rd way)

#### **Priority connection**

The priority connection guarantees the pressure compensated flow supply to the primary circuit.

The exceeding flow (not required by the primary circuit) is bypassed through the valve P port, to secondary circuit operating at lower pressure and not requiring compensated flow regulations.

# 9 HYDRAULIC OPTIONS

## 9.1 Option /D

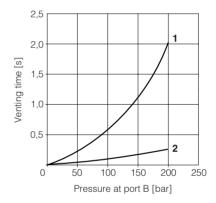
This option provides a quick venting of the use port B when the valve is closed or de-energized. The valve must be connected in 3 way, with P port connected to tank

When the proportional throttle is fully closed, the valve's port B is internally connected to port P (tank), permitting a quickly decompression of the pressure in the use line.

In the diagram aside are represented the venting times of QVHZO and QVKZOR option /D respect to standard versions.

1 = standard versions

2 = option /Q



# 10 OPTIONS for -A

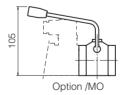
# 10.1 Coil voltage

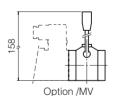
Option /6 optional coil to be used with Atos drivers with power supply 12 VDC
Option /18 optional coil to be used with electronic drivers not supplied by Atos

#### 10.2 Hand lever only for QVHZO-A

It allows to operate the valve in absence of electrical power supply. For detailed description of QVHZO-A with hand lever option see tech. table E138

Option /MO horizontal hand lever
Option /MV vertical hand lever

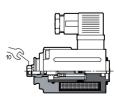


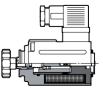


The following supplementary options allow to operate QVHZO-A and QVKZOR-A in absence of electrical power supply by means of a micrometric screw replacing the standard solenoid manual override, see tech. table TK150

Option /N manual micrometric adjustment

Option /NV as /N plus handwheel and graduated scale





Option /N

Option /NV

# 11 ELECTRONIC OPTIONS for AEB and AES

Standard driver execution provides on the 7 pin main connector:

Power supply

- 24 VDc must be appropriately stabilized or rectified and filtered; **2,5 A** fuse time lag is required in series to each driver power supply Apply at least a 10000  $\mu$ F/40 V capacitance to single phase rectifiers or a 4700  $\mu$ F/40 V capacitance to three phase rectifiers

Reference input signal - analog differential input with ±10 VDc nominal range (pin D, E), proportional to desired coil current

Monitor output signal - analog output signal proportional to the actual valve's coil current (1V monitor = 1A coil current)

**Note:** a minimum booting time of 500 ms has be considered from the driver energizing with the 24 VDC power supply before the valve has been ready to operate. During this time the current to the valve coils is switched to zero.

#### 11.1 Option /I

It provides  $4 \div 20$  mA current reference signal, instead of the standard  $0 \div +10$  V.

Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of ±10 V or ±20 mA.

It is normally used in case of long distance between the machine control unit and the valve or where the reference signal can be affected by electrical noise; the valve functioning is disabled in case of reference signal cable breakage.

#### 11.2 Option /Q

To enable the driver, supply 24 VDC on pin C referred to pin B: Enable input signal allows to enable/disable the current supply to the solenoid, without removing the electrical power supply to the driver; it is used to maintain active the communication and the other driver functions when the valve has to be disabled. This condition does not comply with European Norms EN13849-1 (ex EN954-1).

#### 11.3 Option /Z

It provides, on the 12 pin main connector, the following additional features:

#### **Enable Input Signal**

To enable the driver, supply 24 VDC on pin 3 referred to pin 2: Enable input signal allows to enable/disable the current supply to the solenoid, without removing the electrical power supply to the driver; it is used to maintain active the communication and the other driver functions when the valve has to be disabled. This condition does not comply with European Norms EN13849-1 (ex EN954-1).

#### Fault Output Signal

Fault output signal indicates fault conditions of the driver (solenoid short circuits/not connected, reference signal cable broken for 4÷20mA input, etc.). Fault presence corresponds to 0 VDC, normal working corresponds to 24 VDC (pin 11 referred to pin 2): Fault status is not affected by the Enable input signal

#### Power supply for driver's logics and communication

Separate power supply (pin 9,10) allow to cut solenoid power supply (pin 1,2) while maintaining active diagnostics, USB and fieldbus communication. A safety fuse is required in series to each driver power supply: 500 mA fast fuse.

#### 11.4 Option /W - only for valves coupled with pressure compensator type HC-011 or KC-011 (see tab. D150).

It provides, on the 12 pin main connector, the above option /Z features plus the hydraulic power limitation function.

The driver receives the flow reference signal by the analog input INPUT+ and a pressure transducer, installed in the hydraulic system, has to be connected to the driver's analog input TR.

When the actual requested hydraulic power pxQ (TR x INPUT+) reaches the max power limit (p1xQ1), internally set by software, the driver automatically reduces the flow regulation of the valve. The higher is the pressure feedback the lower is the valve's regulated flow:

Flow regulation = Min ( PowerLimit [sw setting] ; Flow Reference [INPUT+]) ; Flow Reference [INPUT+])

#### For detailed information on hydraulic power limitation, see tab. GS115

# 11.5 Option /C - only in combination with option /W

Option /C is available to connect pressure transducer with  $4 \div 20$  mA current output signal, instead of the standard  $0 \div 10V$ . Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of  $\pm 10 \text{ V}$  or  $\pm 20 \text{ mA}$ .

### 11.6 Possible combined options: /IQ, /IZ, /IW, /CW and /CWI

# 12 PROGRAMMING TOOLS - see tech table GS500

Valve's functional parameters and configurations, can be easily set and optimized using Atos E-SW programming software connected via USB port to the digital driver. For fieldbus versions, the software permits valve's parameterization through USB port also if the driver is connected to the central machine unit via fieldbus.

The software is available in different versions according to the driver's options:

 E-SW-BASIC
 support:
 NP (USB)
 PS (Serial)
 IR (Infrared)

 E-SW-FIELDBUS
 support:
 BC (CANopen)
 BP (PROFIBUS DP)
 EH (EtherCAT)

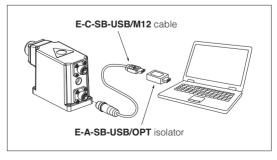
EW (POWERLINK)

E-SW-\*/PQ support: valves with SP, SF, SL alternated control (e.g. E-SW-BASIC/PQ)

#### WARNING: drivers USB port is not isolated!

The use of isolator adapter is highly recommended for PC protection (see table **GS500**)

#### **USB** connection



# 13 ELECTRONIC CONNECTIONS

# 13.1 Main connector signals - 7 pin - standard and /Q options - AEB and AES $\stackrel{\hbox{\scriptsize (A1)}}{}$

PIN	Standard	/Q	TECHNICAL SPECIFICATIONS	NOTES
Α	A <b>V</b> +		Power supply 24 VDC Rectified and filtered: VRMS = 20 ÷ 32 VMAX (ripple max 10 % VPP)	Input - power supply
В	B <b>V0</b>		Power supply 0 Vpc	Gnd - power supply
С	AGND		Analog ground	Gnd - analog signal
	ENABLE		Enable (24 Vpc) or disable (0 Vpc) the driver, referred to V0	Input - on/off signal
D	INPUT+		Reference input signal: $\pm 10$ Vpc / $\pm 20$ mA maximum range Defaults are 0 $\div$ +10 Vpc for standard and 4 $\div$ 20 mA for /I option	Input - analog signal Software selectable
Е	E INPUT-		Negative reference input signal for INPUT+	Input - analog signal
F	F MONITOR referred to: AGND V0		Monitor output signal: $\pm 5$ Vpc maximum range Default is $0 \div + 5$ Vpc (1V = 1A)	Output - analog signal <b>Software selectable</b>
G	G <b>EARTH</b>		Internally connected to driver housing	

# 13.2 Main connector signals - 12 pin - /Z and /W options - AEB and AES $\boxed{\mathbb{A}2}$

PIN	/Z	/W	TECHNICAL SPECIFICATIONS	NOTES
1	V+		Power supply 24 VDC Rectified and filtered: VRMS = 20 ÷ 32 VMAX (ripple max 10 % VPP)	Input - power supply
2	V0		Power supply 0 Vpc	Gnd - power supply
3	ENABLE		Enable (24 VDC) or disable (0 VDC) the driver, referred to V0	Input - on/off signal
4	INPUT+		Reference input signal: ±10 Vpc / ±20 mA maximum range Defaults are 0 ÷ +10 Vpc for standard and 4 ÷ 20 mA for /I option	Input - analog signal Software selectable
5	INPUT-		Negative reference input signal for INPUT+	Input - analog signal
6	MONITOR		Monitor output signal: ±5 Vpc maximum range, referred to VL0 Default is 0 ÷ +5 Vpc (1V = 1A)	Output - analog signal
7	NC		Do not connect	
8	NC		Do not connect	
0		MONITOR2	2nd monitor output signal: ±5 Vpc maximum range, default is 0 ÷ 5 Vpc	Output - analog signal
9	VL+		Power supply 24 Vpc for driver's logic and communication	Input - power supply
10	VL0		Power supply 0 Vpc for driver's logic and communication	Gnd - power supply
11	FAULT		Fault (0 Vpc) or normal working (24 Vpc), referred to V0	Output - on/off signal
PE	EARTH		Internally connected to driver housing	

# 13.3 Communication connectors - AEB (B) and AES (B) - (C)

В	USB connector - M12 - 5 pin always present				
PIN	SIGNAL	TECHNICAL SPECIFICATION (1)			
1	+5V_USB	Power supply			
2	ID	Identification			
3	GND_USB	Signal zero data line			
4	D-	Data line -			
5	D+	Data line +			

© BP fieldbus execution, connector - M12 - 5 pin (2)					
PIN	SIGNAL	TECHNICAL SPECIFICATION (1)			
1	+5V	Termination supply signal			
2	LINE-A	Bus line (high)			
3	DGND	Data line and termination signal zero			
4	LINE-B	Bus line (low)			
5	SHIELD				

(C1)	BC fieldbus execution, connector - M12 - 5 pin (2)				
PIN	SIGNAL	TECHNICAL SPECIFICATION (1)			
1	CAN_SHLD	Shield			
2	NC	do not connect			
3	CAN_GND	Signal zero data line			
4	CAN_H	Bus line (high)			
5	CAN_L	Bus line (low)			

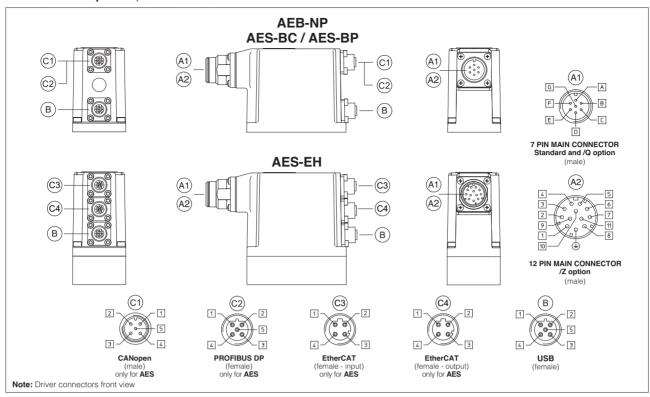
©3	©3 ©4 EH fieldbus execution, connector - M12 - 4 pin (2)						
PIN	PIN SIGNAL TECHNICAL SPECIFICATION (1)						
1	TX+	Transmitter					
2	RX+	Receiver					
3	TX-	Transmitter					
4	RX-	Receiver					
Housing	SHIELD						

# 13.4 Pressure transducer connector - M12 - 5 pin - only for /W option $\bigcirc$

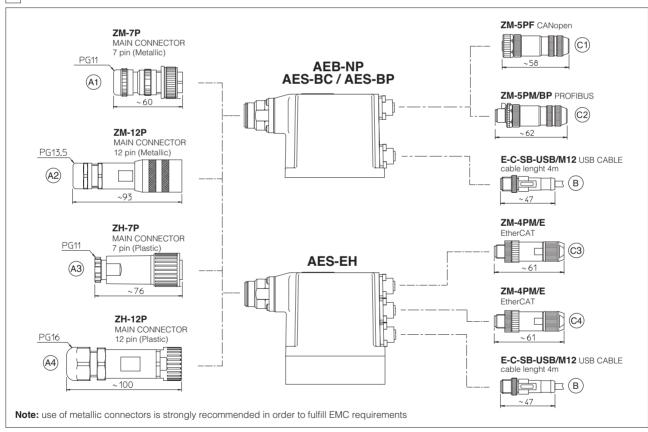
		-		
PIN	SIGNAL	TECHNICAL SPECIFICATION	Voltage	Current
1	VF +24V	Power supply +24Vpc	Connect	Connect
2	TR	Signal transducer maximum range ±10 Vpc / ±20 mA, software selectable Defaults are 0 ÷ 10 Vpc for standard and 4 ÷ 20 mA for /C option	Connect	Connect
3	AGND	Common GND for transducer power and signals	Connect	/
4	NC	Not Connect	/	/
5	NC	Not Connect	/	/

# 13.5 Solenoid connection - only for A

		,			
PIN	SIGNAL	TECHNICAL SPECIFICATION	Connector code 666		
1	COIL	Power supply	253		
2	COIL	Power supply			
3	GND	Ground			



# 14 CONNECTORS



# 15 MODEL CODES OF MAIN CONNECTORS AND COMMUNICATION CONNECTORS - to be ordered separately

VALVE VERSION	A (1) Power supply	AEB AES	AEB/Z AES/Z	BC - CANopen	BP - PROFIBUS DP	EH - EtherCAT			
CONNECTOR CODE	666	ZM-7P (A1)	ZM-12P (A2)	ZM-5PF ©1)	ZM-5PM/BP ©2	ZM-4PM/E C3			
CONNECTOR CODE	000	ZH-7P (A3)	ZH-12P (A4)			ZM-4PM/E C4			
PROTECTION DEGREE	IP67	IP67							
DATA SHEET	K500	GS115, K500							

# **QVHZO**

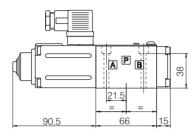
## ISO 4401: 2005

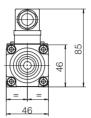
Mounting surface: 4401-03-02-0-05 (see tab. P005)
Fastening bolts: 4 socket head screws M5x50 class 12.9
Tightening torque = 8 Nm
Seals: 4 OR 108;

Diameter of ports A, B, P, T: Ø 7,5 mm (max)

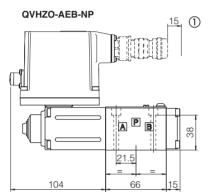
① = Space to remove the 7 or 12 pin main connector. For main and communication connectors see section 14, 15

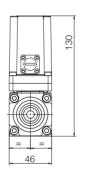
# QVHZO-A



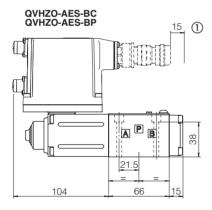


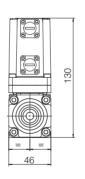
Mass: 2,3 kg



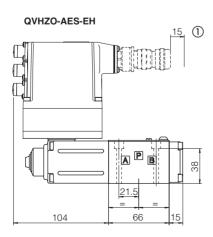


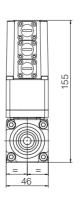
Mass: 2,8 kg





Mass: 2,8 kg





Mass: 2,9 kg

# **QVKZOR**

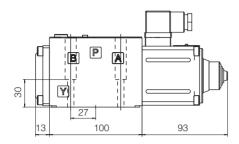
#### ISO 4401: 2005

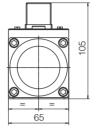
Mounting surface: 4401-05-04-0-05 (see tab. P005)
Fastening bolts: 4 socket head screws M6x40 class 12.9 Tightening torque = 15 Nm Seals: 5 OR 2050;

Diameter of ports A, B, P, T: Ø 11,2 mm (max)

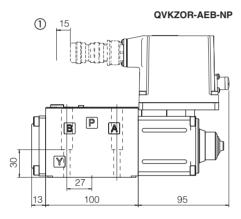
1 = Space to remove the 7 or 12 pin main connector. For main and communication connectors see section 14, 15

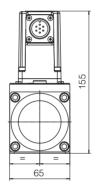
# QVKZOR-A



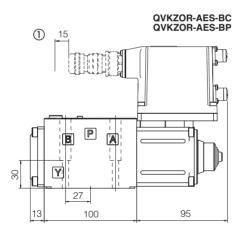


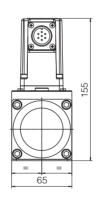
Mass: 3,8 kg



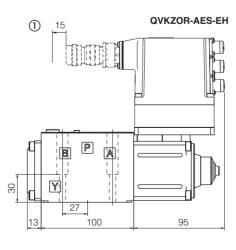


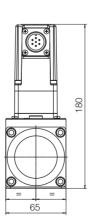
Mass: 4,3 kg





Mass: 4,3 kg





Mass: 4,4 kg