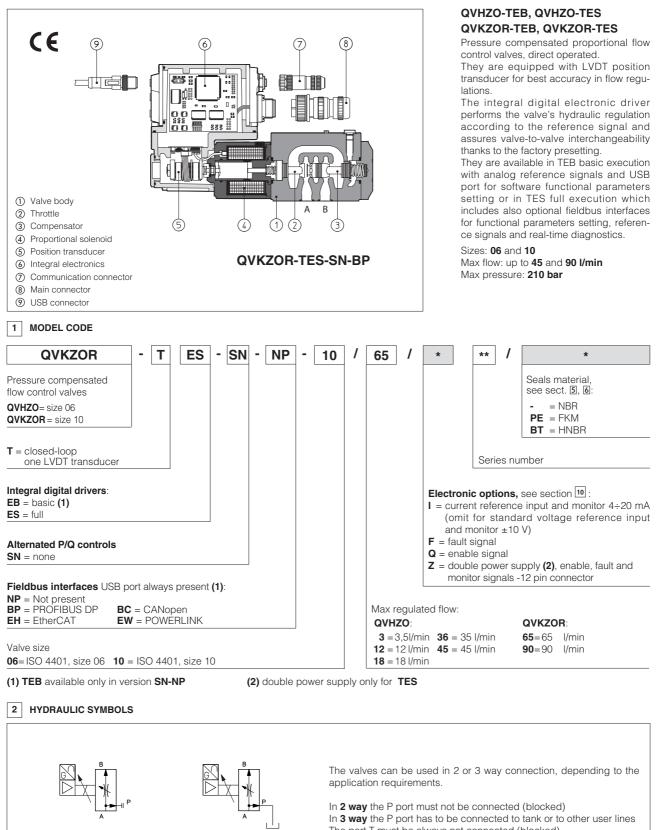


# **Proportional flow valves**

digital, pressure compensated, direct operated, with position transducer



2 way connection

The port T must be always not connected (blocked)

For application examples of 2 and 3 way connections, see section 9

<sup>3</sup> way connection

### 3 GENERAL NOTES

QVHZO-TEB, TES and QVKZOR-TEB, TES proportional valves are CE marked according to the applicable Directives (e.g. Immunity/Emission EMC Directive and Low Voltage Directive). Installation, wirings and start-up procedures must be performed according to the general prescriptions shown in table F003 and in the installation notes supplied with relevant components. The electrical signals of the valve (e.g. monitor signals) must not be directly used to activate safety functions or components, as prescribed by the European standards (Safety requirements of fluid technology systems and components-hydraulics, EN-982).

### 4 FIELDBUS - only for TES

Fieldbus allows valve direct communication with machine control unit for digital reference, valve diagnostics and settings. These execution allow to operate the valves through fieldbus or analog signals available on the main connector. For detailed information about fieldbus features and specification see tech table **GS510**.

#### 5 MAIN CHARACTERISTICS - based on mineral oil ISO VG 46 at 50 °C

Assembly position	Any position	Any position				
Subplate surface finishing	Roughness index, Ra 0	Roughness index, Ra 0,4 flatness ratio 0,01/100 (ISO 1101)				
MTTFd valves according to EN ISO 13849	150 years, see technica	50 years, see technical table P007				
Ambient temperature range	standard = $-20^{\circ}C \div +60^{\circ}C$					
	<b>/BT</b> option = $-40^{\circ}C \div +60^{\circ}C$					
Storage temperature range	<b>Standard</b> = $-20^{\circ}C \div +70^{\circ}C$					
	<b>/BT</b> option = $-40^{\circ}C \div +60^{\circ}C$					
Coil resistance R at 20°C	<b>QVHZO</b> = $3 \div 3,3 \Omega$ <b>QVKZOR</b> = $3,8 \div 4,1 \Omega$					
Max. solenoid current	<b>QVHZO</b> = 2,6 A <b>QVKZOR</b> = 3 A					
Max. power	50 Watt					
Insulation class	H (180°) Due to the occ	curing surface temperatu	ires of the solenoid coils,	, the European standards		
	ISO 13732-1 and EN98	2 must be taken into acc	count			
Protection degree to DIN EN60529	IP66/67 with mating co	nnector				
Tropicalization	Tropical coating on ele	ctronics PCB				
Duty factor	Continuous rating (ED=	=100%)				
EMC, climate and mechanical load	See technical table GO	04				
Communication interface	USB Atos ASCII coding	CANopen EN50325-4 + DS408	PROFIBUS DP EN50170-2/IEC61158	EtherCAT, POWERLINK IEC 61158		
Communication physical layer	not insulated USB 2.0 + USB OTG	optical insulated CAN ISO11898	optical insulated RS485	Fast Ethernet, insulated 100 Base TX		

Valve model			QVHZO				QVKZOR		
Max regulated flow [I/min]		[l/min]	3,5	12	18	35	45	65	90
Min regulated	l flow (1)	[cm³/min]	15	20	30	50	60	85	100
Regulating ∆p [bar]		[bar]	4 - 6 10 - 12		15	6 - 8	10 - 12		
Max flow on port A [I/min]		[l/min]	50			60	70	100	
Max pressure [bar]			210				2	10	
Response tim	e 0÷100% ste	p signal <b>(2)</b> [ms]	25					35	
Hysteresis	[% of the reg	ulated max flow]	≤ 0,5			≤ 0,5			
Linearity	[% of the reg	ulated max flow]	≤ 0,5				<	0,5	
Repeatability	[% of the reg	ulated max flow]	≤ 0,1		<	0,1			
Thermal drift			zero point displacement < 1% at $\Delta T = 40^{\circ}C$						

Notes: Above performance data refer to valves coupled with Atos electronic drivers, see sections.

(1) For different  $\Delta p$ , the max flow is in accordance to the diagrams in section 8.2

(2) Referred to spool in neutral position and 50°C oil temperature.

(3) 0-100% step signal

#### 6 SEALS AND HYDRAULIC FLUID - for other fluids not included in below table, consult our technical office

Seals, recommended fluid temperature	NBR seals (standard) = $-20^{\circ}C \div +60^{\circ}C$ , with HFC hydraulic fluids = $-20^{\circ}C \div +50^{\circ}C$ FKM seals (/PE option) = $-20^{\circ}C \div +80^{\circ}C$ HNBR seals (/BT option) = $-40^{\circ}C \div +60^{\circ}C$ , with HFC hydraulic fluids = $-40^{\circ}C \div +50^{\circ}C$			
Recommended viscosity	20÷100 mm²/s - max allowed range 15 ÷ 380 mm²/s			
Fluid contamination class	ISO 4406 class 20/18/15 NAS 1638 class 9, in line filters of 10 μm (β10 ≥75 recommended)			
Hydraulic fluid	Suitable seals type Classification Ref. Standard			
Mineral oils	NBR, FKM, HNBR	HL, HLP, HLPD, HVLP, HVLPD	DIN 51524	
Flame resistant without water	FKM HFDU, HFDR			
Flame resistant with water	NBR, HNBR	HFC	ISO 12922	

### 7 ELECTRONIC DRIVERS

Valve model	ТЕВ	TES		
Drivers model	E-RI-TEB-N	E-RI-TES-N		
Туре	Digital			
Format	Integral to valve			
Data sheet	GS208	GS210		

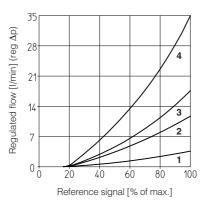
Note: for main and communication connector see sections 12, 13

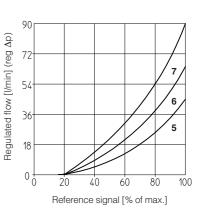
#### 8 DIAGRAMS - based on mineral oil ISO VG 46 at 50 °C

### 8.1 Regulation diagrams

- 1 = QVHZO-\*-06/3 2 = QVHZO-\*-06/12 3 = QVHZO-\*-06/18
- 4 = QVHZO-\*-06/36 5 = QVHZO-\*-06/45 6 = QVKZOR-\*-10/65



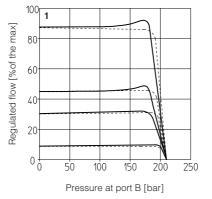


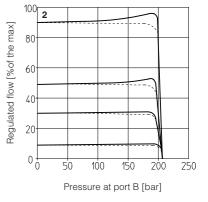


#### 8.2 Regulated flow/outlet pressure diagrams with inlet pressure = 210 bar

- 1 = QVHZO 2 = QVKZOR

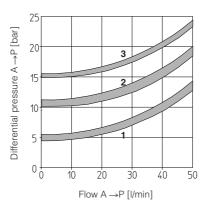
Dotted line for 3-way versions

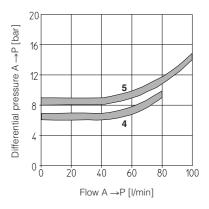




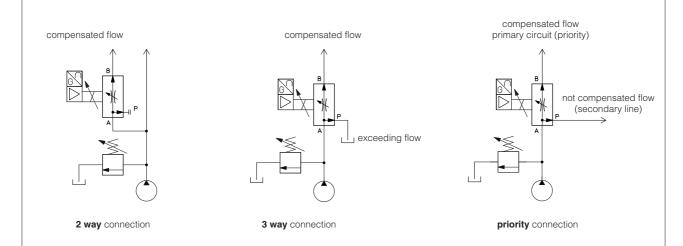
#### 8.3 Flow $A \rightarrow P/\Delta p$ diagrams 3-way configuration 1 = QVHZO-\*-06/3 QVHZO-\*-06/12

- 2 = QVHZO-\*-06/18 QVHZO-\*-06/36
- 3 = QVHZO-\*-06/45 4 = QVKZOR-\*-10/65
- 5 = QVKZOR-\*-10/90





### 9 APPLICATIONS AND CONNECTIONS



#### 2 way connection

The 2 way connection is normally used to control the flow in one part of the hydraulic circuit or to regulate the speed of a specific actuator. The metered flow in the controlled line is kept constant, independently to the load variations If the valve is directly installed on the pump main line, the exceeding flow is returned to tank though the pressure relief valve.

#### 3 way connection

The 3 way connection is normally used when the valve directly controls the pump flow (main line) The metered flow in the controlled line is kept constant, independently to the load variations The exceeding flow (not metered by the valve) it is returned to tank trough the valve P port = T line (3rd way)

#### **Priority connection**

The priority connection guarantees the pressure compensated flow supply to the primary circuit. The exceeding flow (not required by the primary circuit) is bypassed through the valve P port, to secondary circuit operating at lower pressure and not requiring compensated flow regulations.

#### 10 ELECTRONIC OPTIONS

Standard driver execution provides on the 7 pin main connector:

 - 24 VDC must be appropriately stabilized or rectified and filtered; 2,5 A fuse time lag is required in series to each driver power supply. Apply at least a 10000 μF/40 V capacitance to single phase rectifiers or a 4700 μF/40 V capacitance to three phase rectifiers

Reference input signal - analog differential input with ±10 VDc nominal range (pin D, E), proportional to desired valve spool position

Monitor output signal - analog output signal proportional to the actual valve's spool position with ±10VDC nominal range

Note: a minimum booting time between 400 and 800 ms has be considered from the driver energizing with the 24 Vbc power supply before the valve has been ready to operate. During this time the current to the valve coils is switched to zero.

#### 10.1 Option /F

Power supply

It provides a Fault output signal in place of the Monitor output signal, to indicate fault conditions of the driver (cable interruption of spool transducers or reference signal - for /I option): Fault presence corresponds to 0 VDC, normal working corresponds to 24 VDC

#### 10.2 Option /I

It provides  $4 \div 20$  mA current reference and monitor signals, instead of the standard  $0 \div +10V$ .

Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of ±10 V or ±20 mA. It is normally used in case of long distance between the machine control unit and the valve or where the reference signal can be affected by

It is normally used in case of long distance between the machine control unit and the valve or where the reference signal can be affected by electrical noise; the valve functioning is disabled in case of reference signal cable breakage.

#### 10.3 Option /Q

To enable the driver, supply 24 VDC on pin C referred to pin B: Enable input signal allows to enable/disable the current supply to the solenoid, without removing the electrical power supply to the driver; it is used to maintain active the communication and the other driver functions when the valve has to be disabled. This condition does not comply with European Norms EN13849-1 (ex EN954-1).

#### 10.4 Option /Z

It provides, on the 12 pin main connector, the following additional features:

#### **Enable Input Signal**

To enable the driver, supply 24 VDC on pin 3 referred to pin 2: when the Enable signal is set to zero the valve functioning is disabled (zero current to the solenoid) but the driver current output stage is still active.

#### Fault Output Signal

Fault output signal indicates fault conditions of the driver (solenoid short circuits/not connected, reference signal cable broken for 4÷20mA input, etc.). Fault presence corresponds to 0 VDC, normal working corresponds to 24VDC (pin 11 referred to pin 2): Fault status is not affected by the Enable input signal

#### Power supply for driver's logics and communication - only for TES

Separate power supply (pin 9,10) allow to cut solenoid power supply (pin 1,2) while maintaining active diagnostics, USB and fieldbus communication. A safety fuse is required in series to each driver power supply: 500 mA fast fuse.

#### 10.5 Possible combined options

/FI, /IQ and /IZ

### 11 ELECTRONIC CONNECTIONS AND LEDS

PIN	Standard	/Q	/F	TECHNICAL SPECIFICATIONS	NOTES
A	A V+			Power supply 24 VDc Rectified and filtered: VRMs = 20 ÷ 32 VMAX (ripple max 10 % VPP)	Input - power supply
В	V0			Power supply 0 Vbc	Gnd - power supply
С	AGND AGND ENABLE		AGND	Analog ground	Gnd - analog signal
				Enable (24 VDC) or disable (0 VDC) the valve, referred to V0	Input - on/off signal
	Q_INPUT+		•	Flow reference input signal: ±10 Vpc / ±20 mA maximum range	Input - analog signal
				Defaults are 0 ÷ +10 Vpc for standard and 4 ÷ 20 mA for /I option	Software selectable
E	INPUT-			Negative reference input signal for Q_INPUT+	Input - analog signal
	Q_MONITOF	R referred to:		Flow monitor output signal: ±10 Vpc / ±20 mA maximum range	Output - analog signal
F	AGND V0			Defaults are 0 ÷ +10 Vpc for standard and 4 ÷ 20 mA for /I option	Software selectable
	FAULT		FAULT	Fault (0 Vbc) or normal working (24 Vbc)	Output - on/off signal
G	EARTH			Internally connected to the driver housing	

### 11.1 Main connector signals - 7 pin - standard, /F and /Q options A

### 11.2 Main connector signal - 12 pin - /Z option (A2)

PIN	TEB-SN /Z	TES-SN /Z	TECHNICAL SPECIFICATIONS	NOTES
	V+		Power supply 24 VDc Rectified and filtered: VRMs = 20 ÷ 32 VMAX (ripple max 10 % VPP)	Input - power supply
1	V0		Power supply 0 Vbc	Gnd - power supply
2 3	ENABLE ref	erred to: VL0	Enable (24 Vpc) or disable (0 Vpc) the valve	Input - on/off signal
4	Q INPUT+	1	Flow reference input signal: ±10 VDc / ±20 mA maximum range	Input - analog signal
4	Q_INPUT+		Defaults are 0 ÷ +10 Vpc for standard and 4 ÷ 20 mA for /l option	Software selectable
5	INPUT-		Negative reference input signal for Q_INPUT+	Input - analog signal
6	Q_MONITOR	referred to:	Flow monitor output signal: ±10 Vpc / ±20 mA maximum range	Input - analog signal
0	AGND	VL0	Defaults are 0 ÷ +10 Vpc for standard and 4 ÷ 20 mA for /I option	Software selectable
7	AGND		Analog ground	Output - analog signal
		NC	Do not connect	Gnd - analog signal
8	R_ENABLE		Repeat enable, output repeter signal of enable input, referred to V0	
0		NC	Do not connect	Output - on/off signal
9	NC		Do not connect	
9		VL+	Power supply 24 Vbc for driver's logic and communication	Input - power supply
10	NC		Do not connect	
10		VL0	Power supply 0 Vbc for driver's logic and communication	Gnd - power supply
11 PE	FAULT refer	red to: VL0	Fault (0 Vpc) or normal working (24 Vpc)	Output - on/off signal
	EARTH		Internally connected to the driver housing	

Note: do not disconnect VL0 before VL+ when the driver is connected to PC USB port

### 11.3 Communications connectors (B) - (C)

	B USB connector - M12 - 5 pin always present					
PIN	SIGNAL	<b>TECHNICAL SPECIFICATION</b> (1)				
1	+5V_USB	Supply for external USB Flash Drive				
2	ID	USB Flash Drive identification				
3	GND_USB	Signal zero data line				
4	D-	Data line -				
5	D+	Data line +				

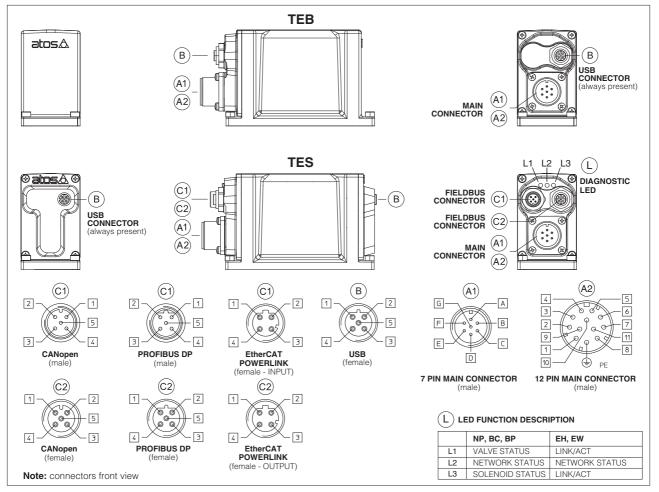
C1 (	©1) ©2) BP fieldbus execution, connector - M12 - 5 pin				
PIN SIGNAL TECHNICAL SPECIFICATION (1)					
1 +5V Termination supply signal					
2	2 LINE-A Bus line (high)				
3	3 DGND Data line and termination signal zero				
4	4 LINE-B Bus line (low)				
5	SHIELD				

Notes: (1) shield connection on connector's housing is recommended

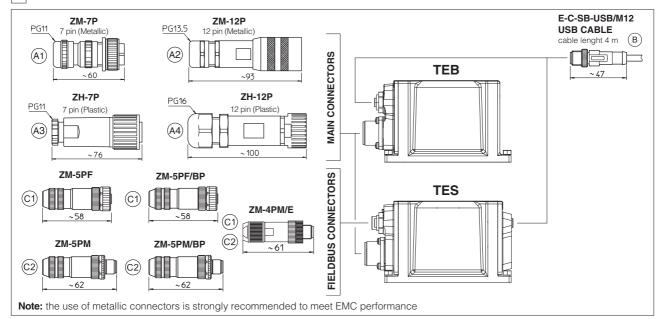
C1 $C2$ BC fieldbus execution, connector - M12 - 5 pin				
PIN	SIGNAL TECHNICAL SPECIFICATION (1)			
1	CAN_SHLD	Shield		
2	not used	©1 - ©2 pass-through connection (2)		
3	CAN_GND	Signal zero data line		
4	CAN_H	Bus line (high)		
5	CAN_L	Bus line (low)		

C1 $C2$ EH, EW fieldbus execution,connector - M12 - 4 pin				
PIN	IN SIGNAL TECHNICAL SPECIFICATION (1)			
1	TX+	Transmitter		
2	RX+	Receiver		
3	TX-	Transmitter		
4	4 RX- Receiver			
	SHIELD			

(2): pin 2 can be fed with external +5V supply of CAN interface



#### 12 CONNECTORS



### 13 MODEL CODES OF MAIN CONNECTORS AND COMMUNICATION CONNECTORS - to be ordered separately

VALVE VERSION	TES	TEB /Z TES /Z	BC - CANopen	<b>BP - PROFIBUS DP</b>	EH - EtherCat EW - POWERLINK
CONNECTOR CODE	ZM-7P (A1)	ZM-12P (A2)	ZM-5PF C1	ZM-5PF/BP C1	ZM-4PM/E C1
CONNECTOR CODE	ZH-7P (A3)	ZH-12P (A4)	ZM-5PM C2	ZM-5PM/BP C2	ZM-4PM/E C2
PROTECTION DEGREE			IP67		
DATA SHEET	GS208, GS210, K500				

### **14 PROGRAMMING TOOLS** - see table **GS500**

#### **USB** connection

Valve's functional parameters and configurations, can be easily set and optimized using Atos E-SW programming software connected via USB port to the digital driver. For fieldbus versions, the software permits valve's parameterization through USB port also if the driver is connected to the central machine unit via fieldbus.

The software is available in different versions according to the driver's options:

E-SW-BASIC	support:	NP (USB)	PS (Serial)	IR (Infrared)
E-SW-FIELDBUS support:		BC (CANopen)	BP (PROFIBUS DP)	EH (EtherCAT)
		EW (POWERLINK)		
E-SW-*/PQ	support:	valves with SP, SF,	SL alternated control (e.g	g. E-SW-BASIC/PQ)

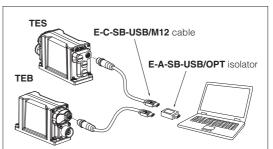
### WARNING: drivers USB port is not isolated!

The use of isolator adapter is highly recommended for PC protection (see table GS500)

### 15 INSTALLATION DIMENSIONS [mm]

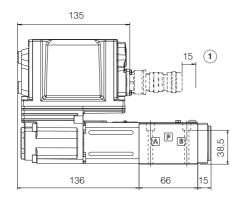
**QVHZO-TEB** 

**QVHZO-TES** 



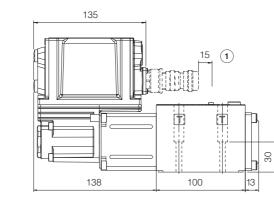
#### ISO 4401: 2005

Mounting surface: 4401-03-02-0-05 (see tab. P005) Fastening bolts: 4 socket head screws M5x50 class 12.9 Tightening torque = 8 Nm Seals: 4 OR 108; Diameter of ports A, B, P, T: Ø 7,5 mm (max)



Mass: 2,3 kg

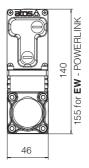
## QVKZOR-TEB QVKZOR-TES



Mass: 4,3 kg

(1) = Space to remove the 7 or 12 pin main connector

Note: for main and communication connectors see section 12, 13



### ISO 4401: 2005

Mounting surface: 4401-05-04-0-05 (see tab. P005) Fastening bolts: 4 socket head screws M6x40 class 12.9 Tightening torque = 15 Nm Seals: 5 OR 2050; Diameter of ports A, B, P, T: Ø 11,2 mm (max)

